332:345 - Exam-2 Review Topics - Fall 2009

- *z*-transforms, definition and properties, region of convergence.
- Inverse *z*-transforms using long division followed by partial fraction expansion.
- Solving difference equations with initial conditions, e.g., load amortization and retirement account examples.
- Discretization methods of analog transfer functions, i.e., starting with G(s), obtain G(z). Forward and backward Euler, trapezoidal/bilinear, and impulse invariance transformation methods.
- Transform the I/O differential equation for *G*(*s*) into a difference equation for *G*(*z*).
- Zero-order-hold discretization method: $G(z) = (1 z^{-1}) Z \left[\frac{G(s)}{s} \right]$.
- Feedback control systems and their digital versions using zero-order holds.
- PID control systems. Calculating the step and ramp responses of the closed-loop control system. Calculating the effect of disturbance inputs on the controlled system.
- MATLAB functions for implementing feedback control systems.
- Fourier series for complex-valued and real-valued periodic signals. Parseval identity for Fourier series.
- Fourier transform, definition and properties.
- Inverse Fourier transforms. Parserval identities.
- Discrete-time Fourier transforms and their inverses.
- Propagation filters, pulse spreading, dispersion compensation filters.
- Chirped pulses and their use in radar. Pulse compression filters.
- Sending pulses through bandlimited channels and working out the received output signals. Distortion effects of channels, such as pulse broadening.

Reading Materials:

Primarily your class notes. Textbook chapters 3-6. Pulse propagation notes.

Practice Problems:

Textbook problems (assigned or not assigned) from above chapters. Examples in class and in text. Sample exam problems (solutions are not available). Matlab programming ideas in labs 1–4.