

What Hockey Teams and Foraging Animals Can Teach Us About Feedback Communication Part II: Timid/Bold Coding

Aaron Wagner
Cornell University

In collaboration with
Nirmal Shende and Yücel Altuğ

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 - ▶ [Other contexts: networks, control over noisy channels, streaming codes, complexity-constrained coding....]

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Is this it?

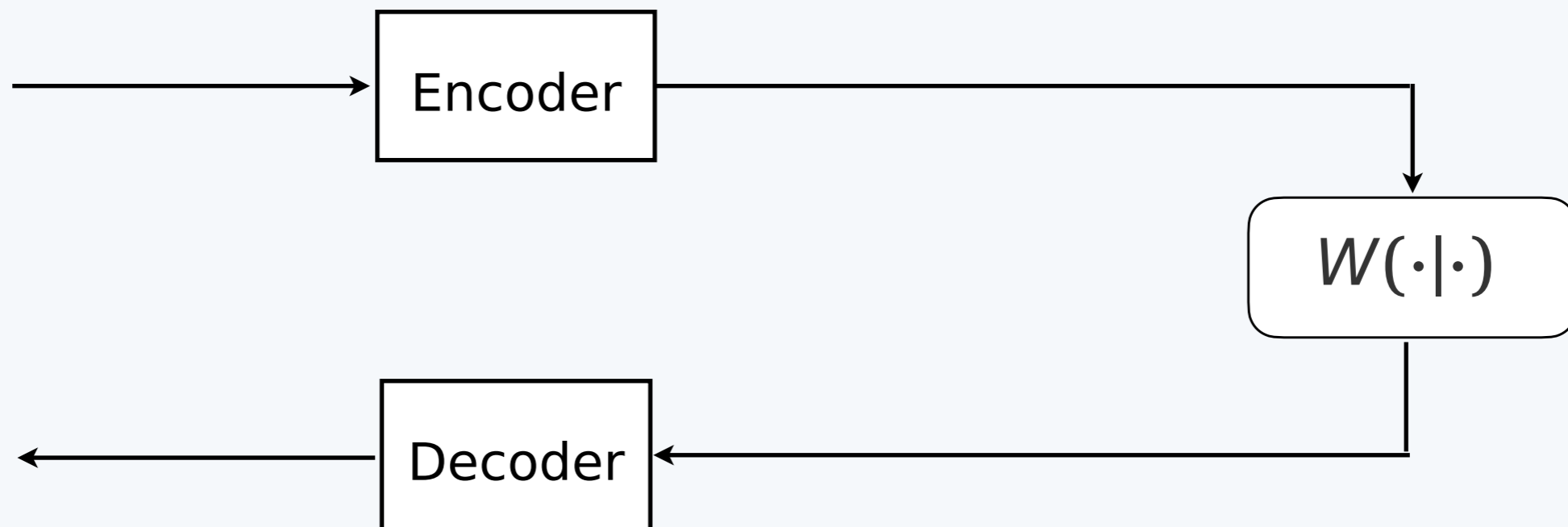
Discrete Memoryless Channels without Feedback

- ▶ Given:
 - input alphabet: \mathcal{X} (finite)
 - output alphabet: \mathcal{Y} (finite)
 - channel matrix: $W(y|x)$ (indep. over time)

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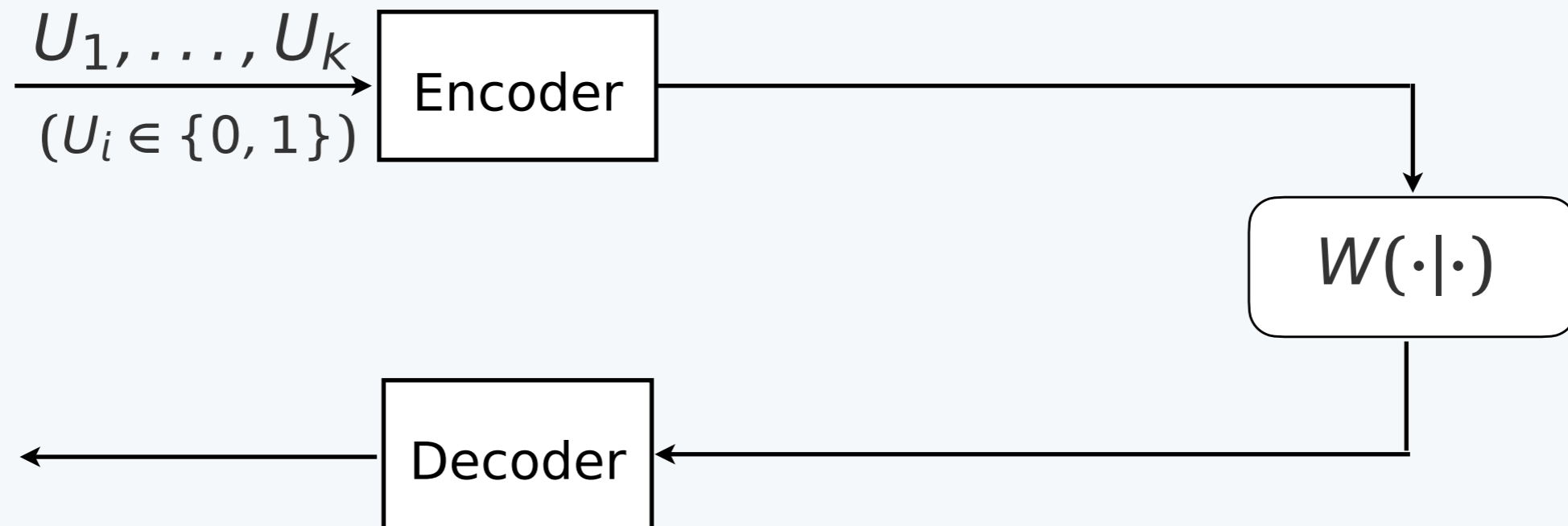
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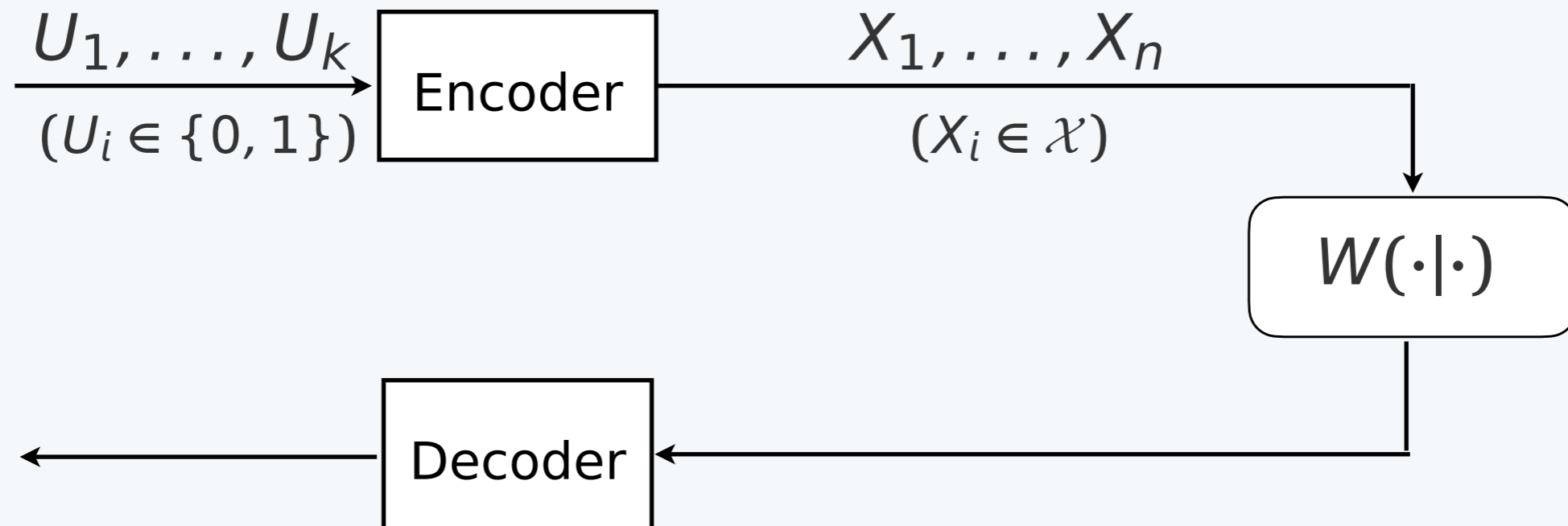
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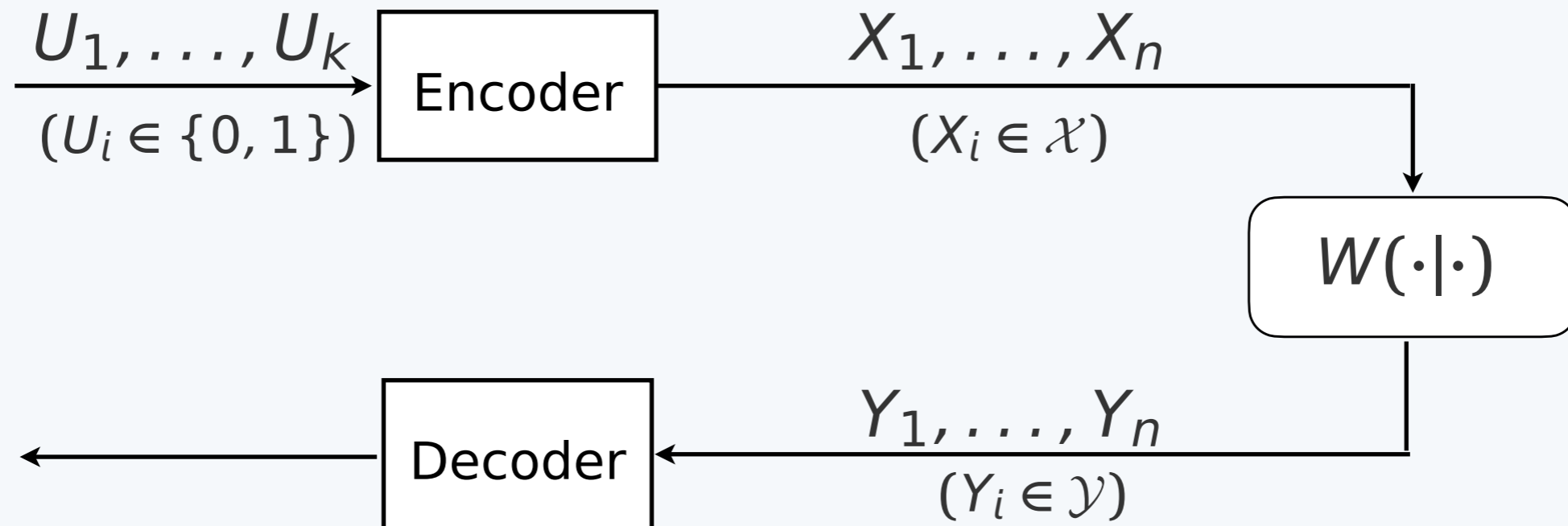
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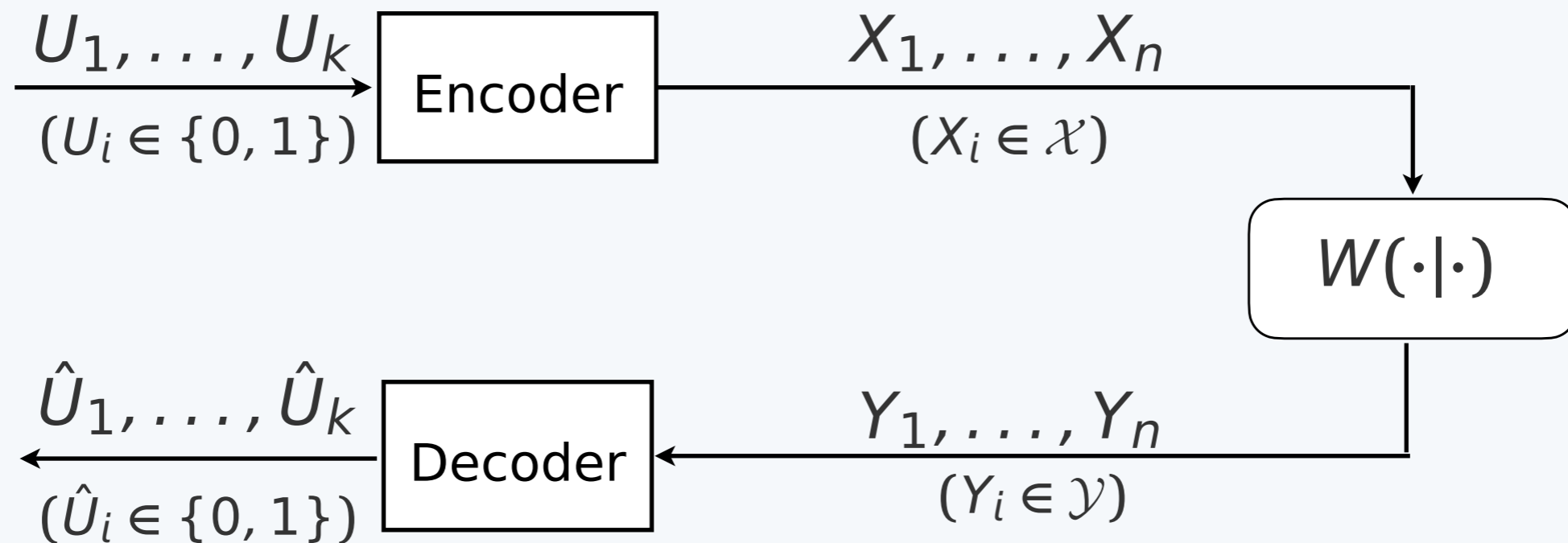
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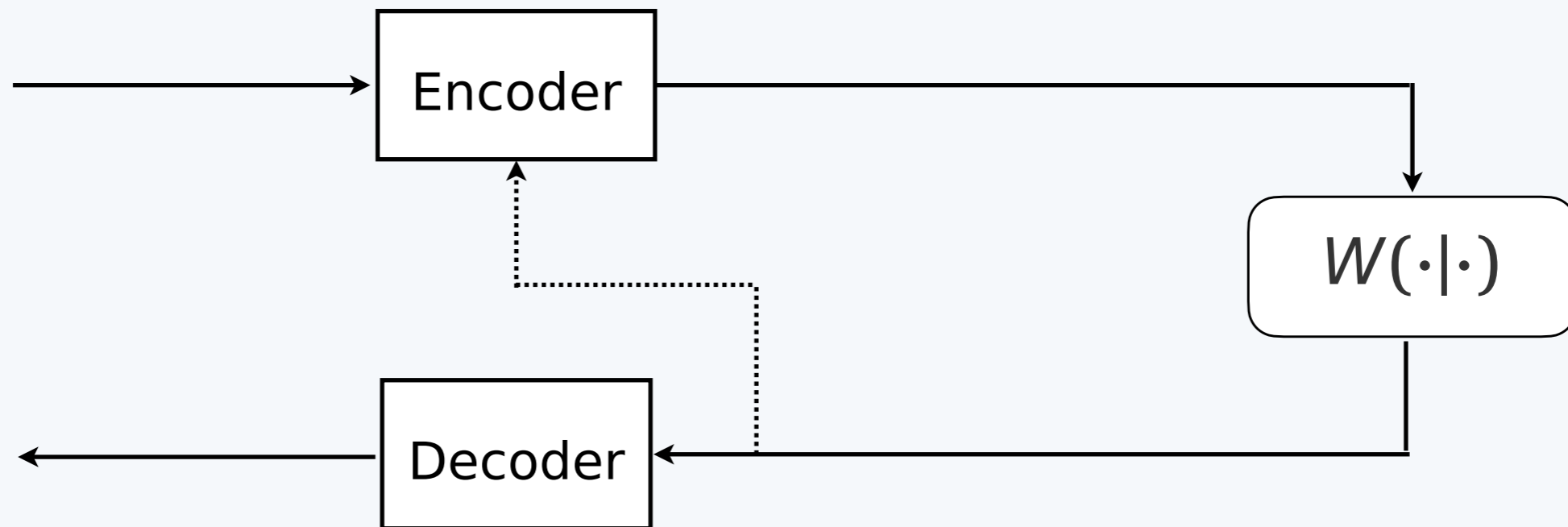
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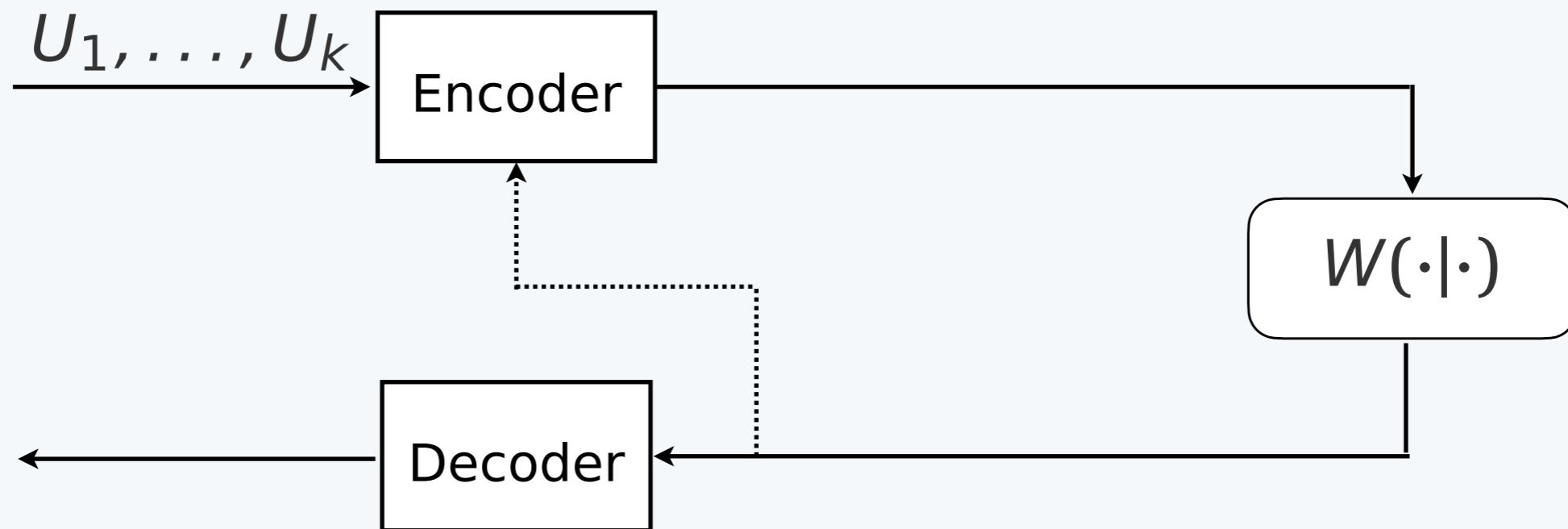
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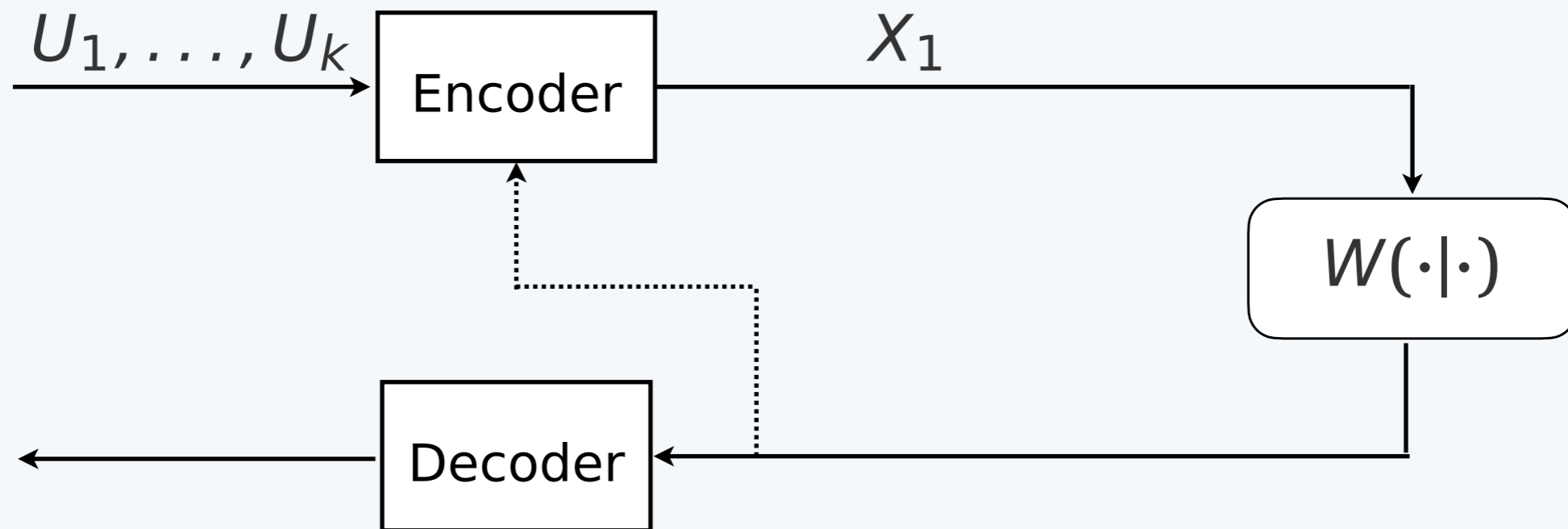
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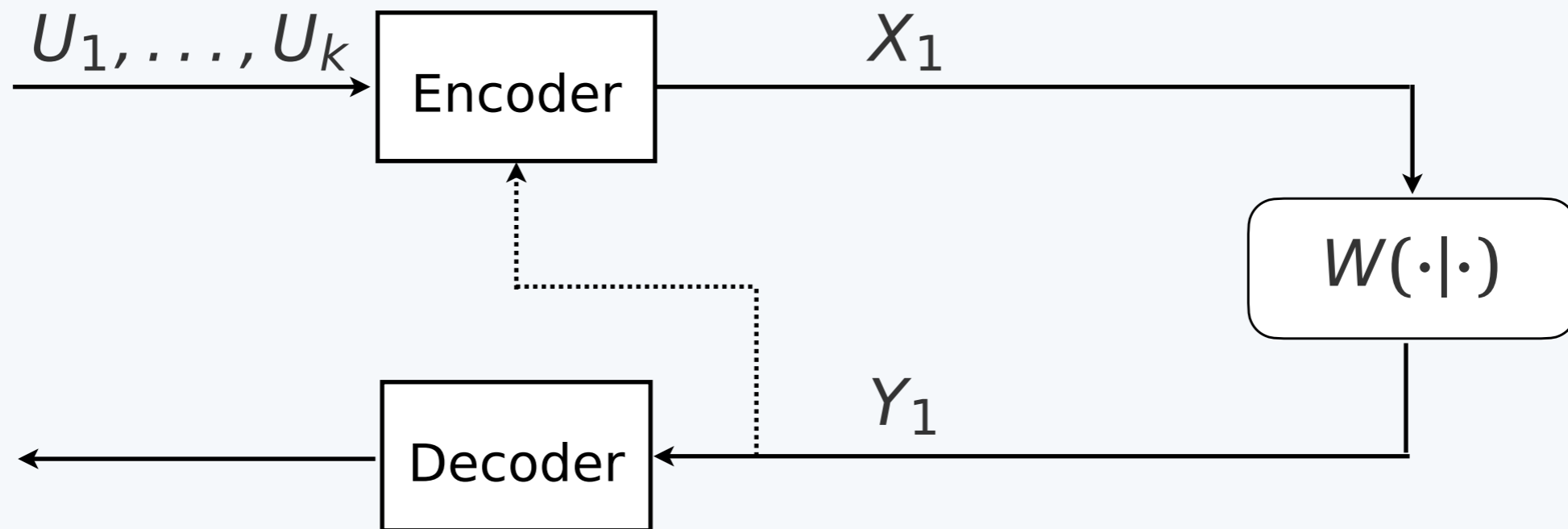
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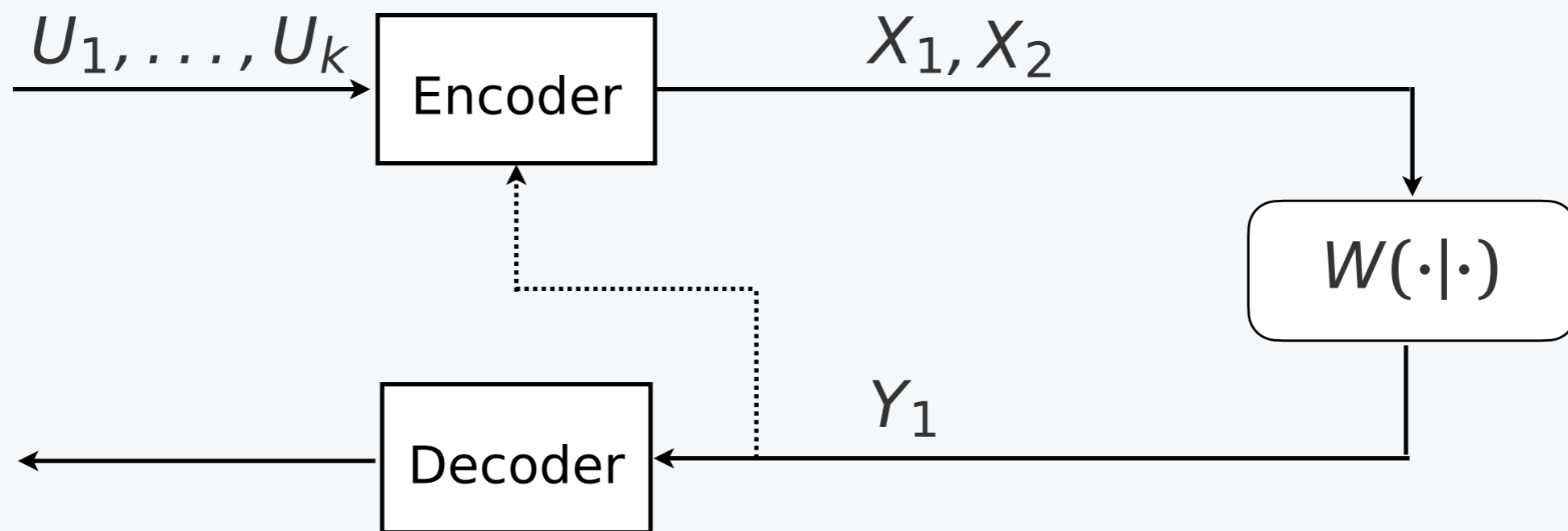
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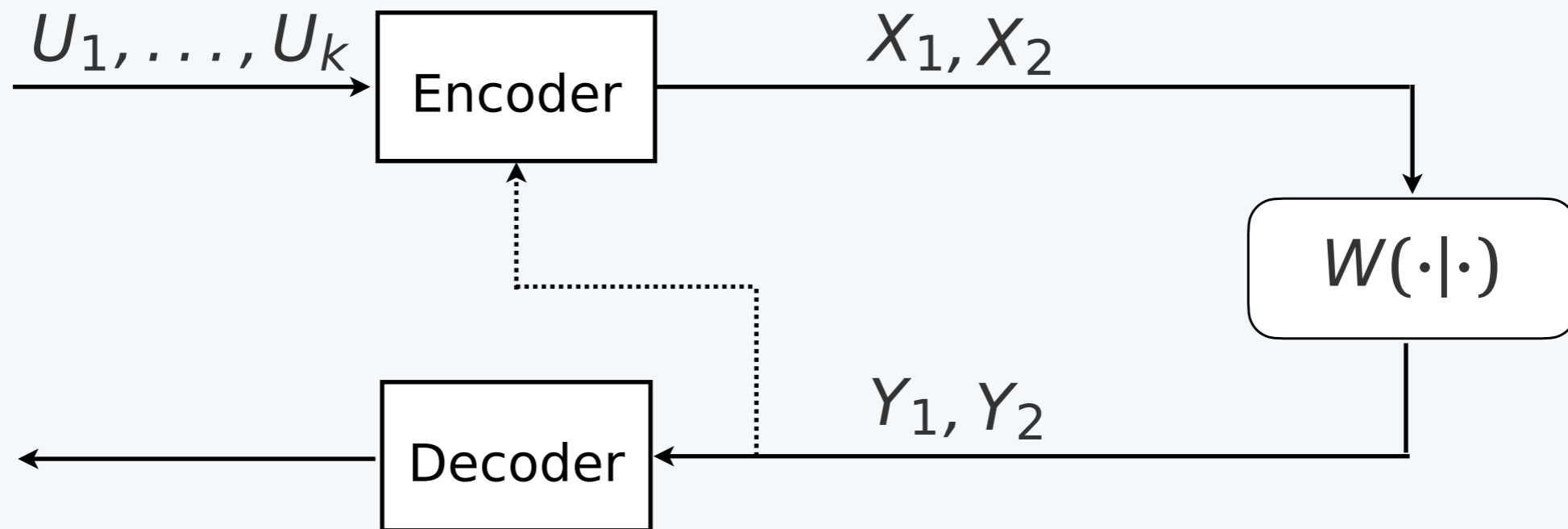
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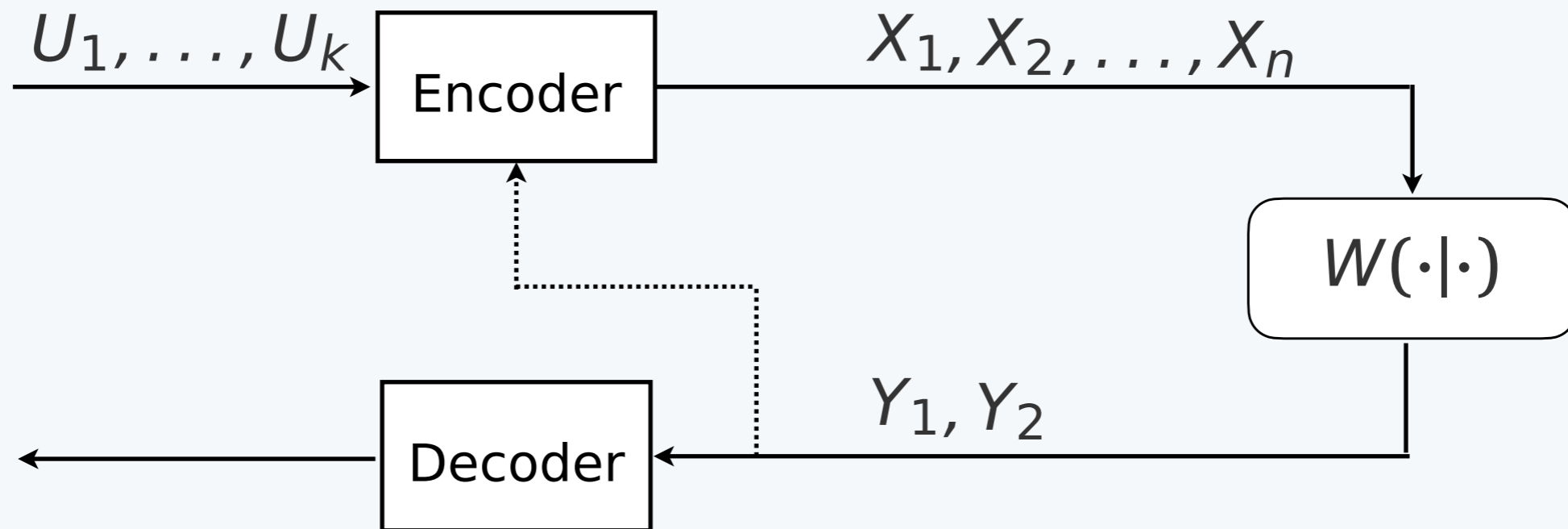
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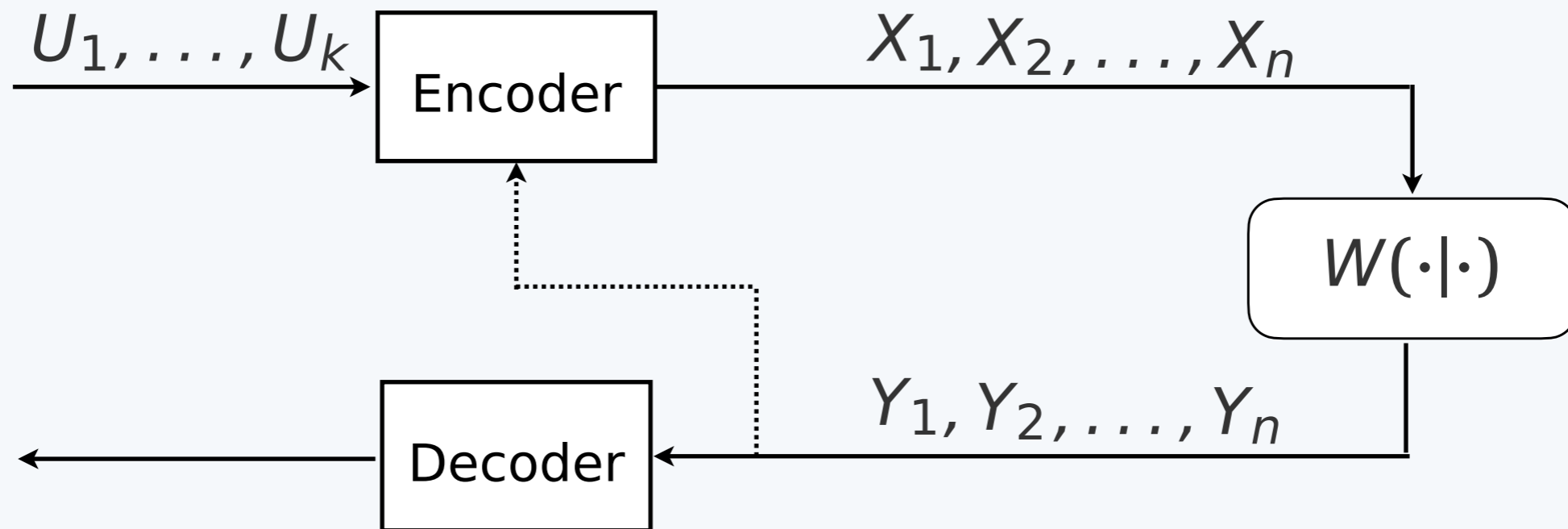
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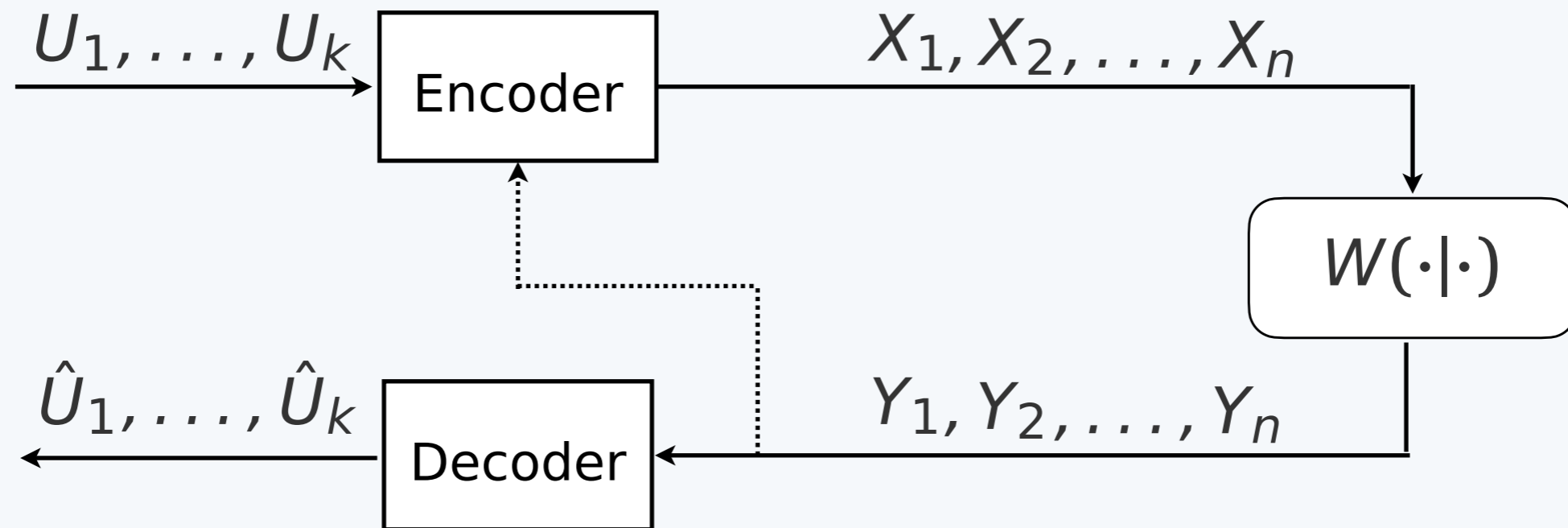
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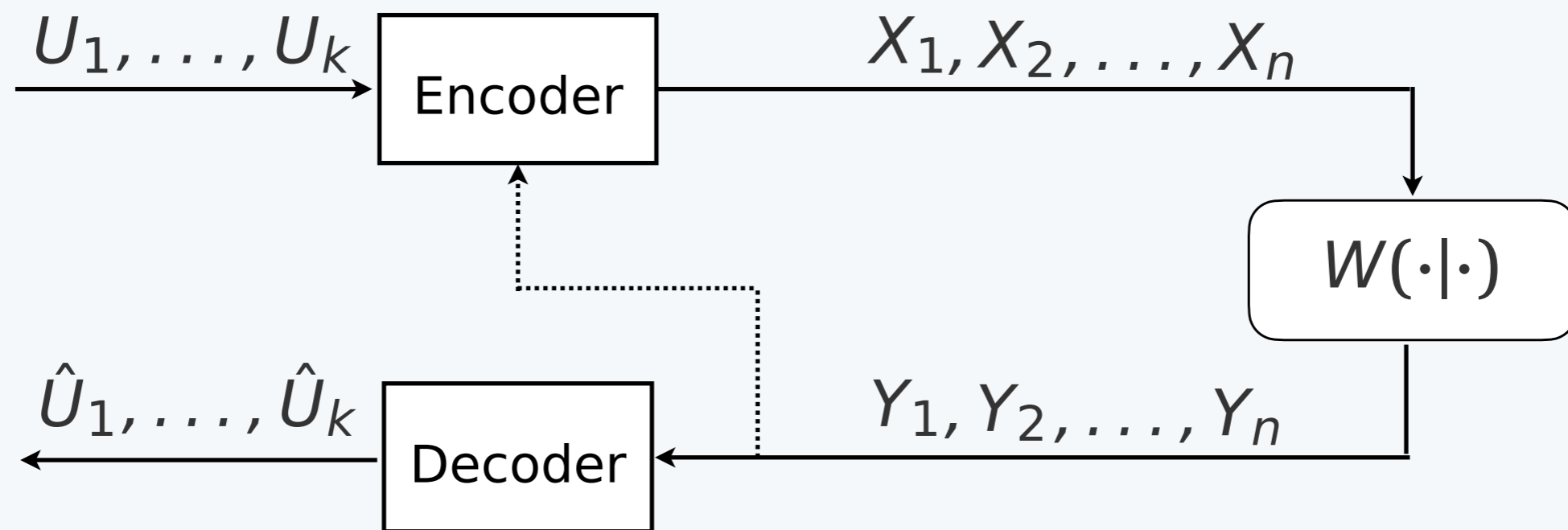
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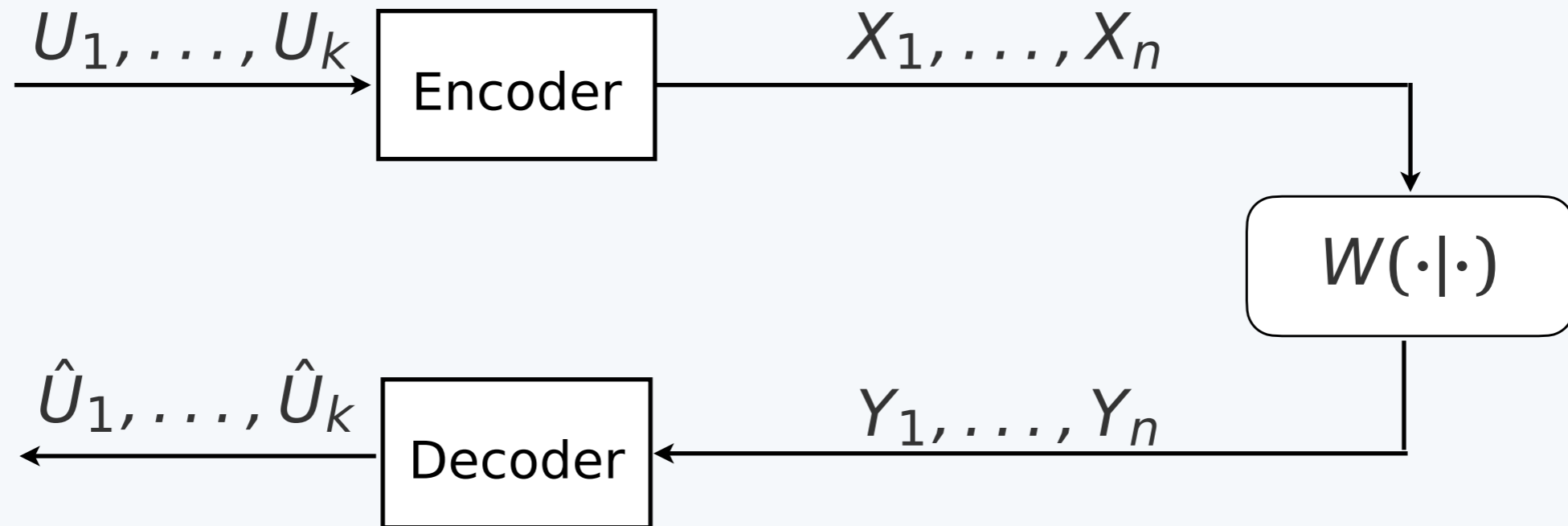
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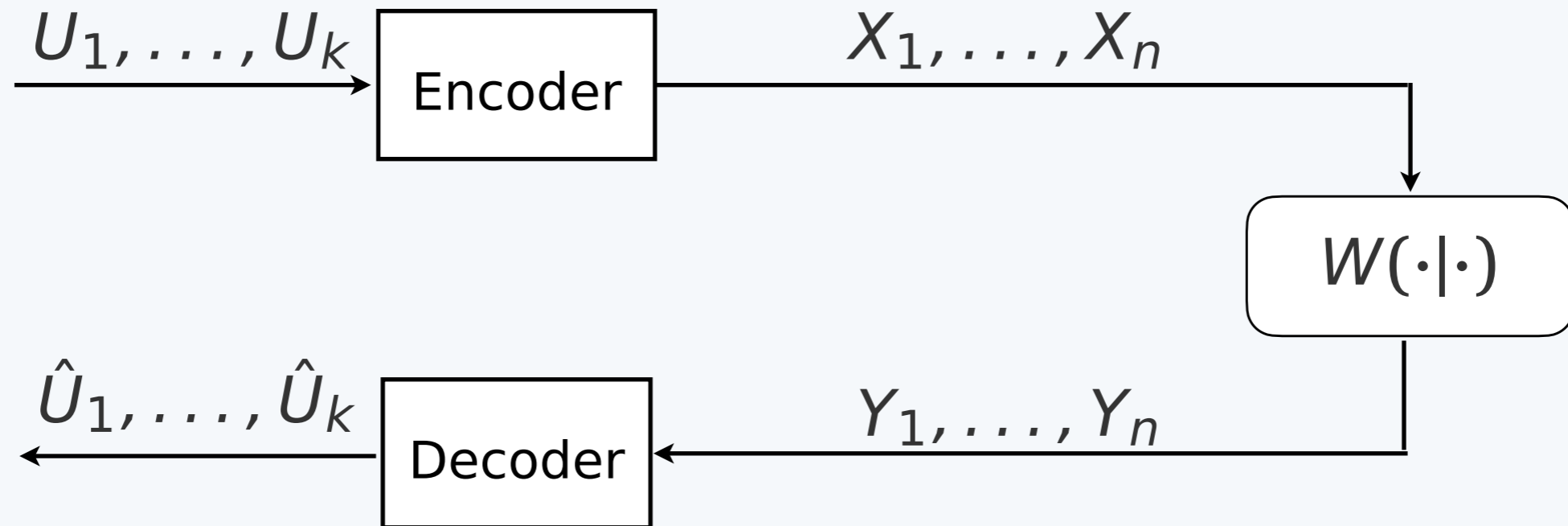


[Real feedback is never so ideal]

Figures of Merit

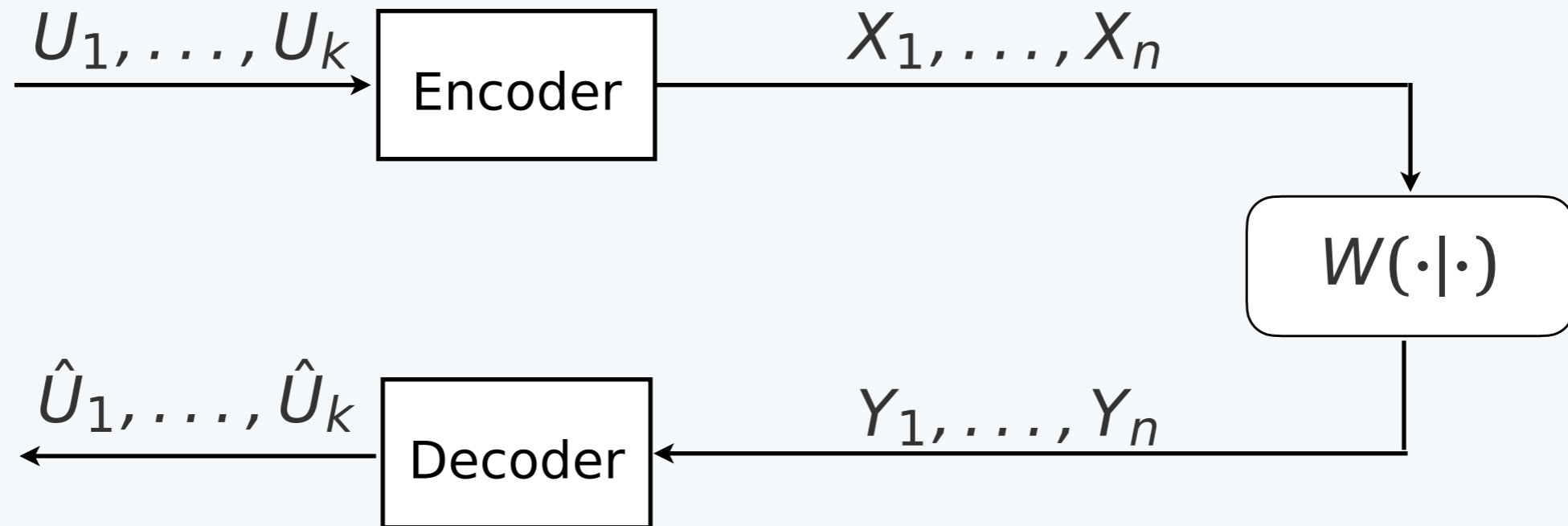


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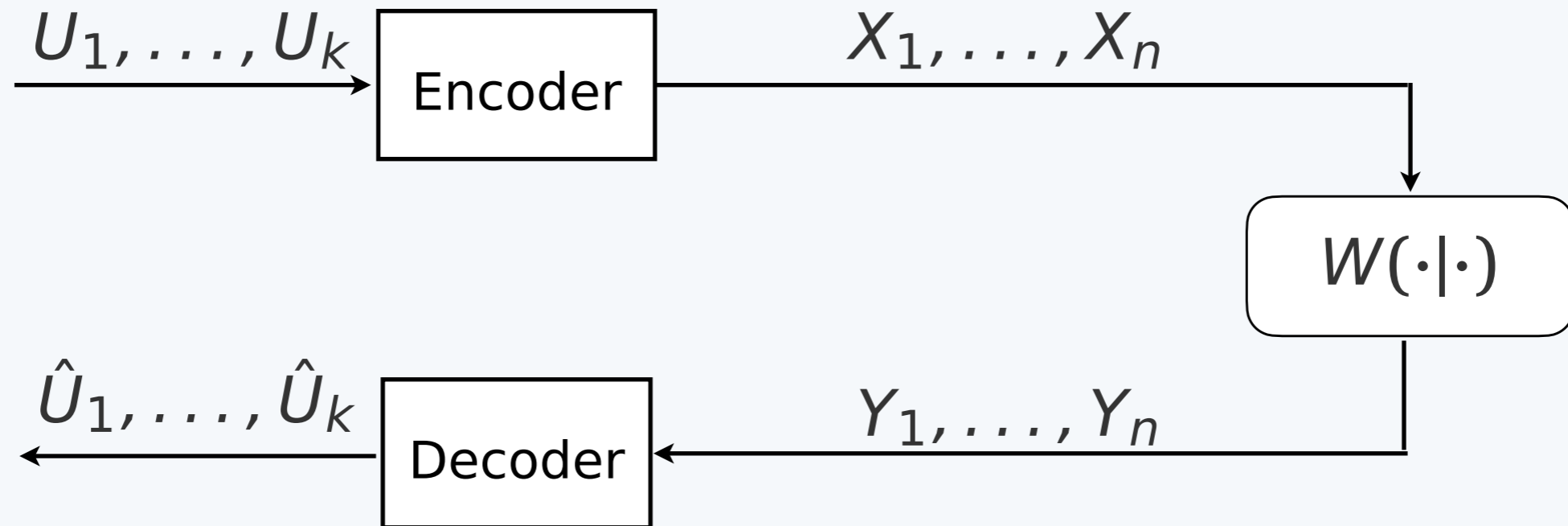
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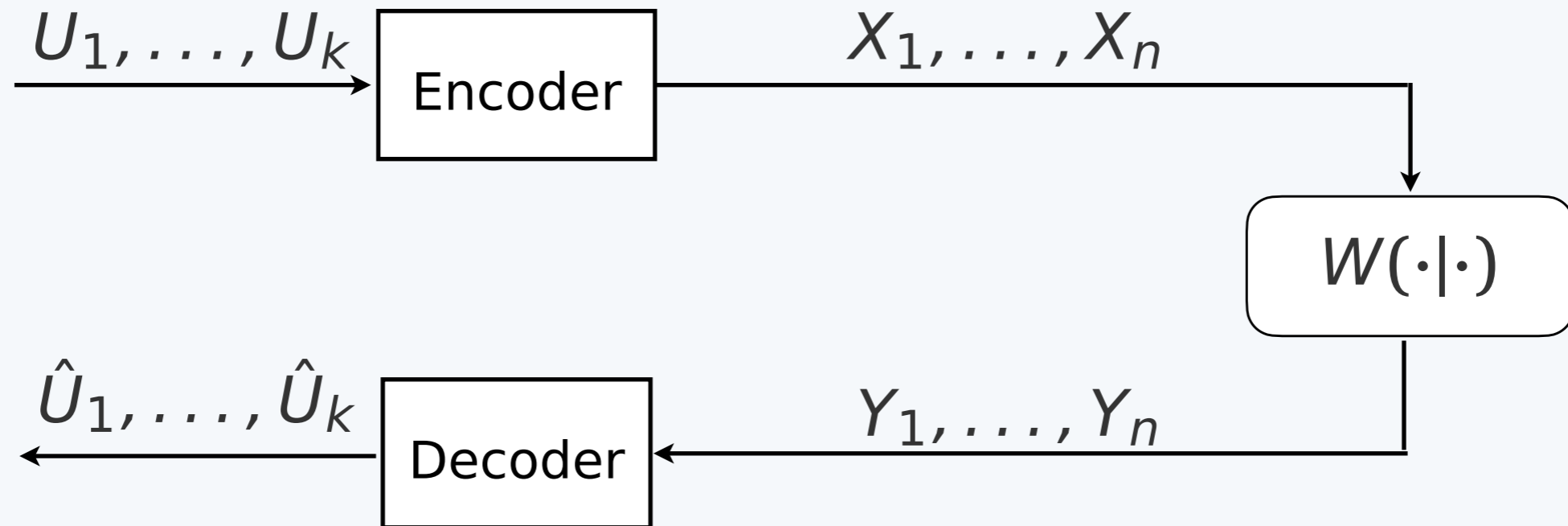
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- ▶ Error probability: $P_e = P(U^k \neq \hat{U}^k)$

Second-Order Coding Rate

► **Def:**

$$R(n, \epsilon) = \max \left\{ \frac{k}{n} : \exists \text{ an } (n, k, P_e) \text{ code with } P_e \leq \epsilon \right\}$$

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► **Theorem** (cf. Shannon '56):

$$\lim_{n \rightarrow \infty} R(n, \epsilon) = \lim_{n \rightarrow \infty} R^{(fb)}(n, \epsilon) = C \quad \text{if } 0 < \epsilon < 1$$

where C is the capacity:

$$C = \max_P I(P; W) = \max_P E_{P \circ W} \left[\log \frac{W(Y|X)}{PW(Y)} \right]$$

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- ▶ For *asymmetric* channels,
 - The high-rate error exponent is not improved by feedback [Nakiboğlu '19, Augustin '78]
 - We will show that the second-order coding rate can be improved by feedback via a novel mechanism.

A Puzzle

Two coins:



$\pm \$1$



$\pm \$2$

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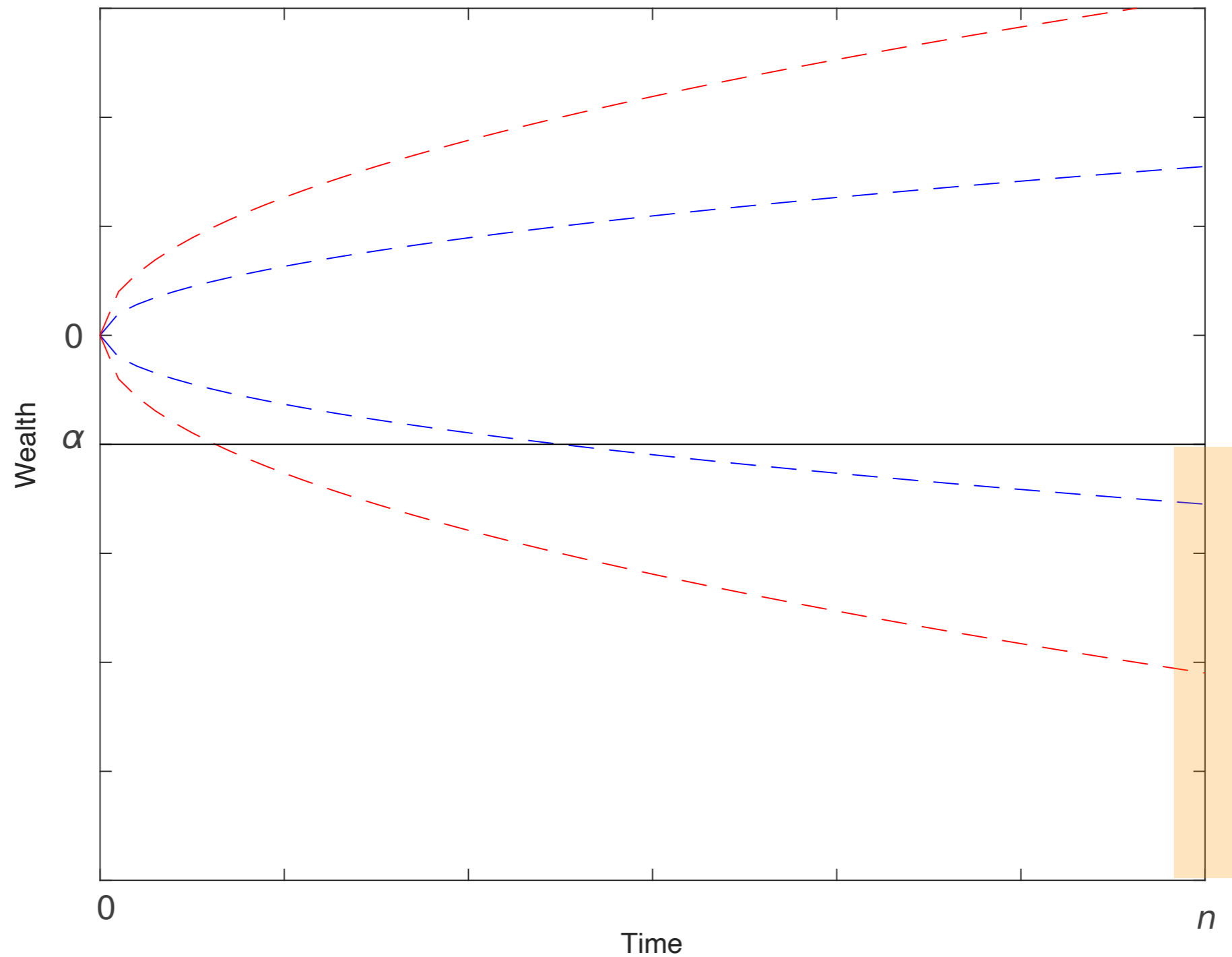
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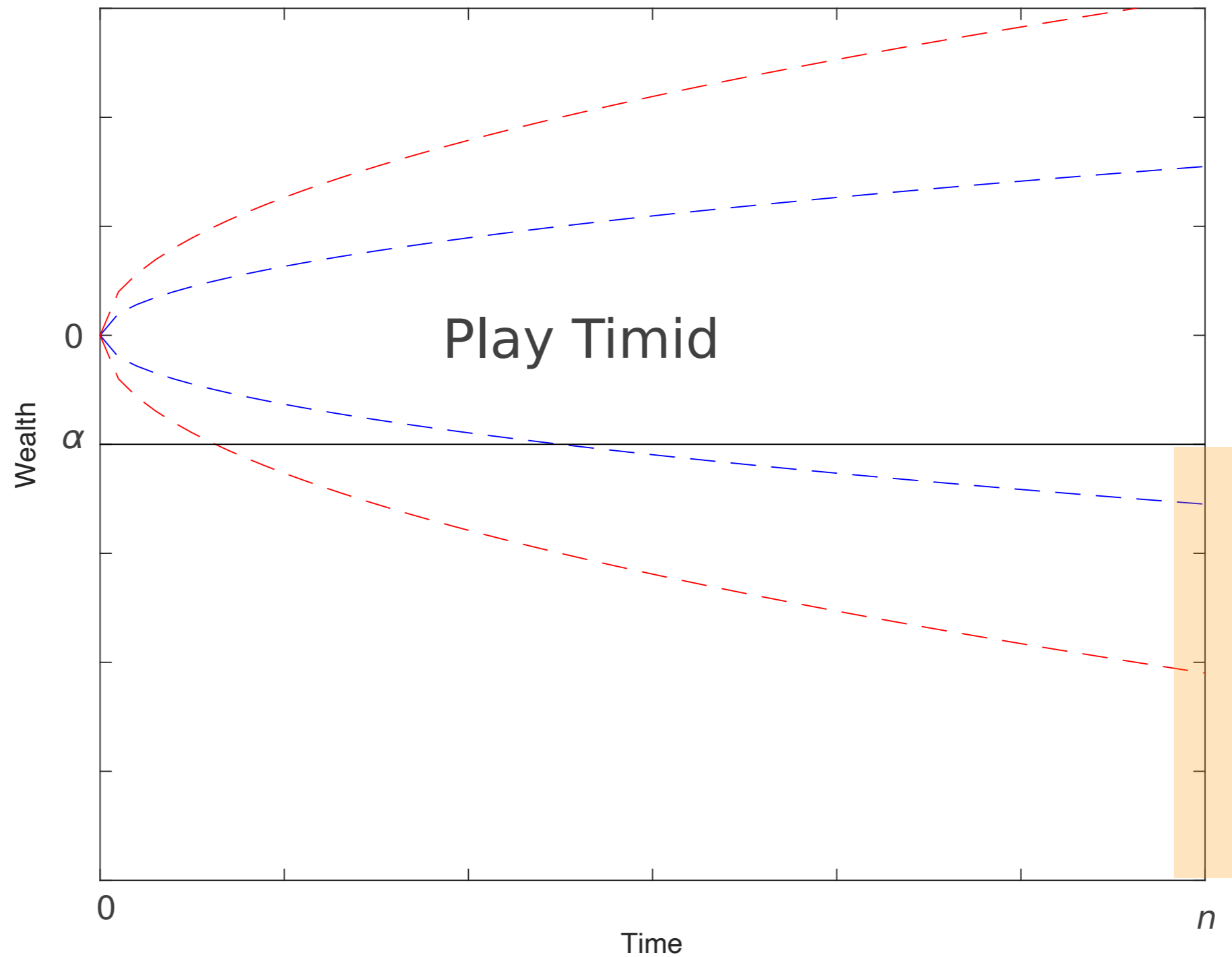
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- ▶ Does “feedback” help?

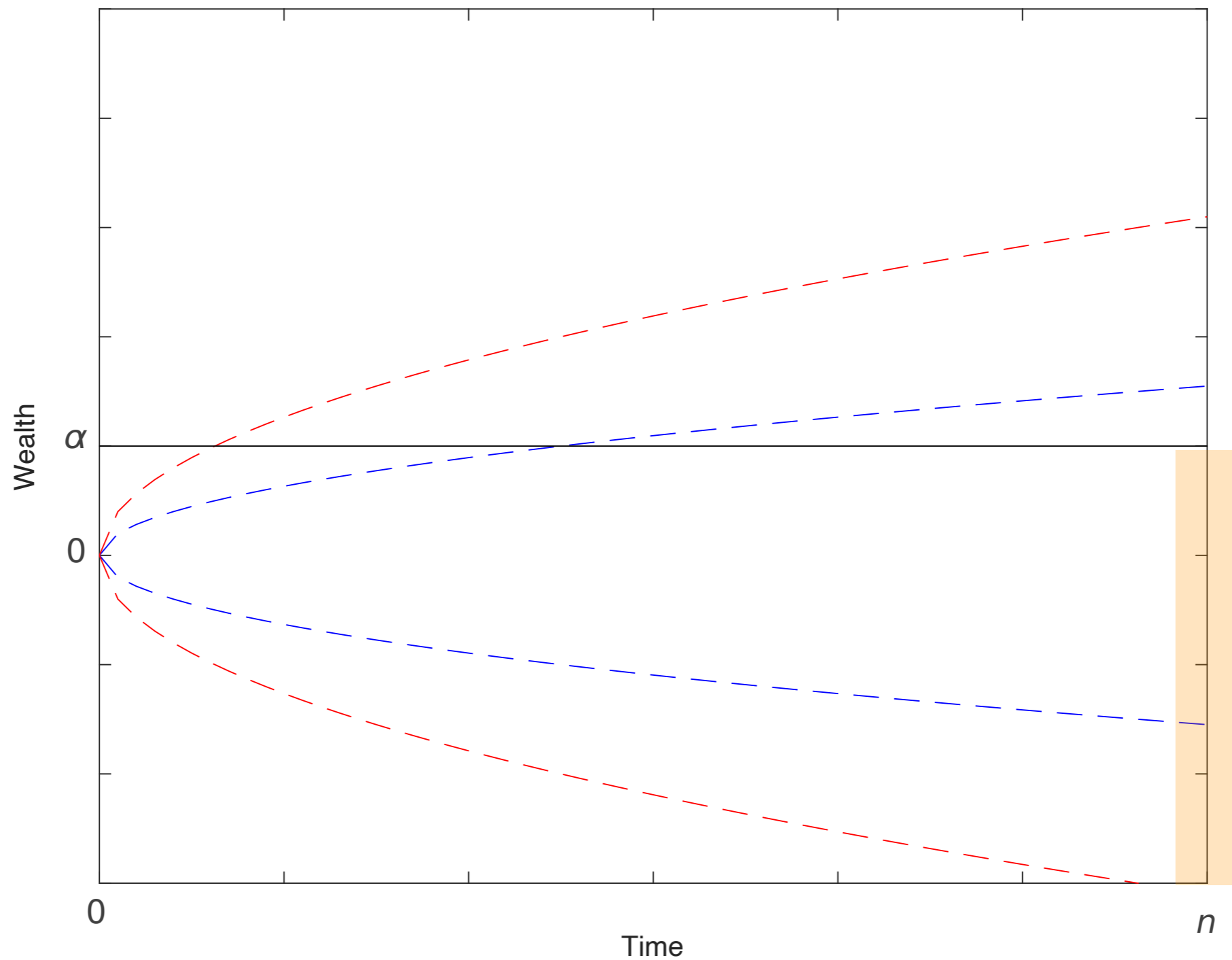
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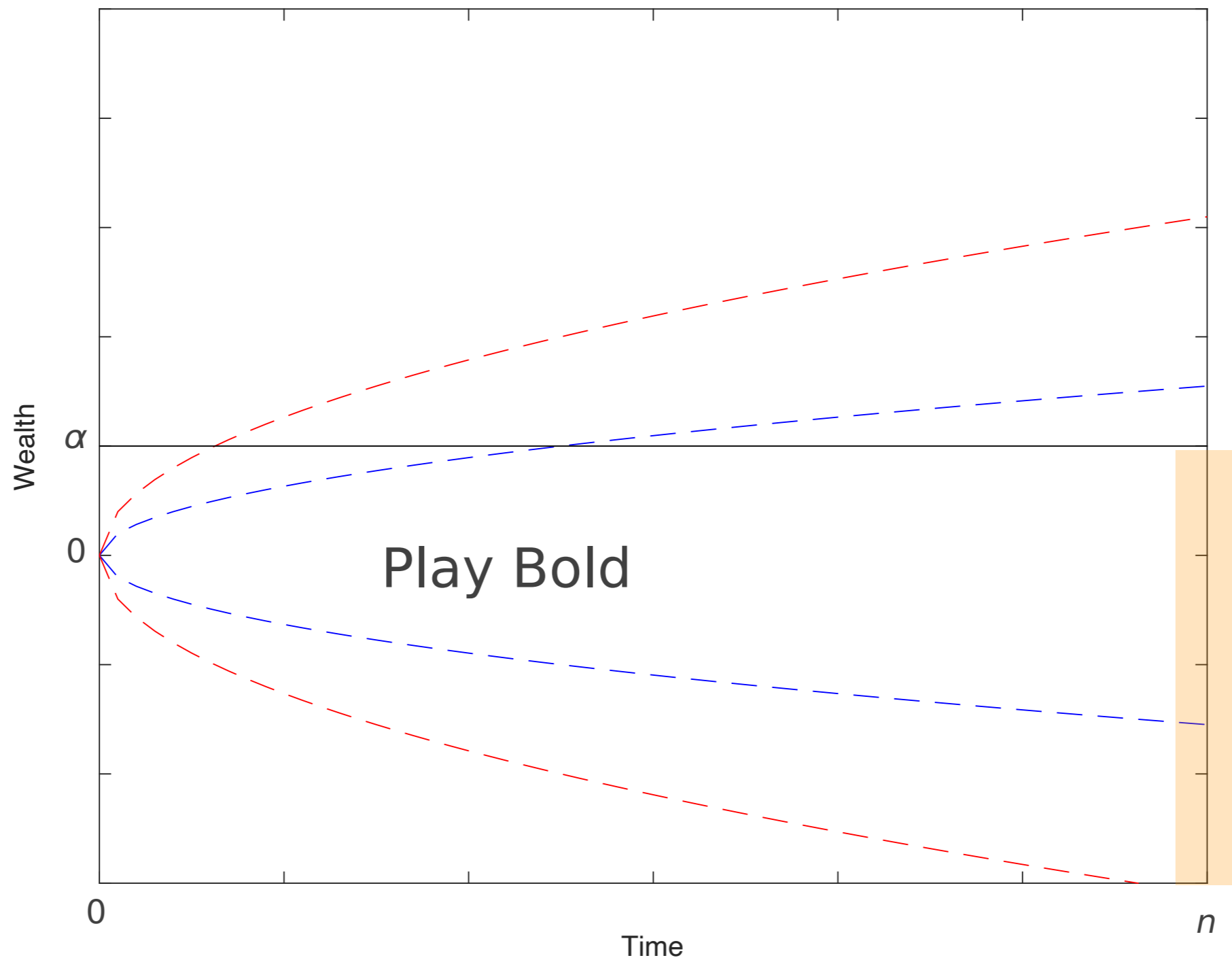
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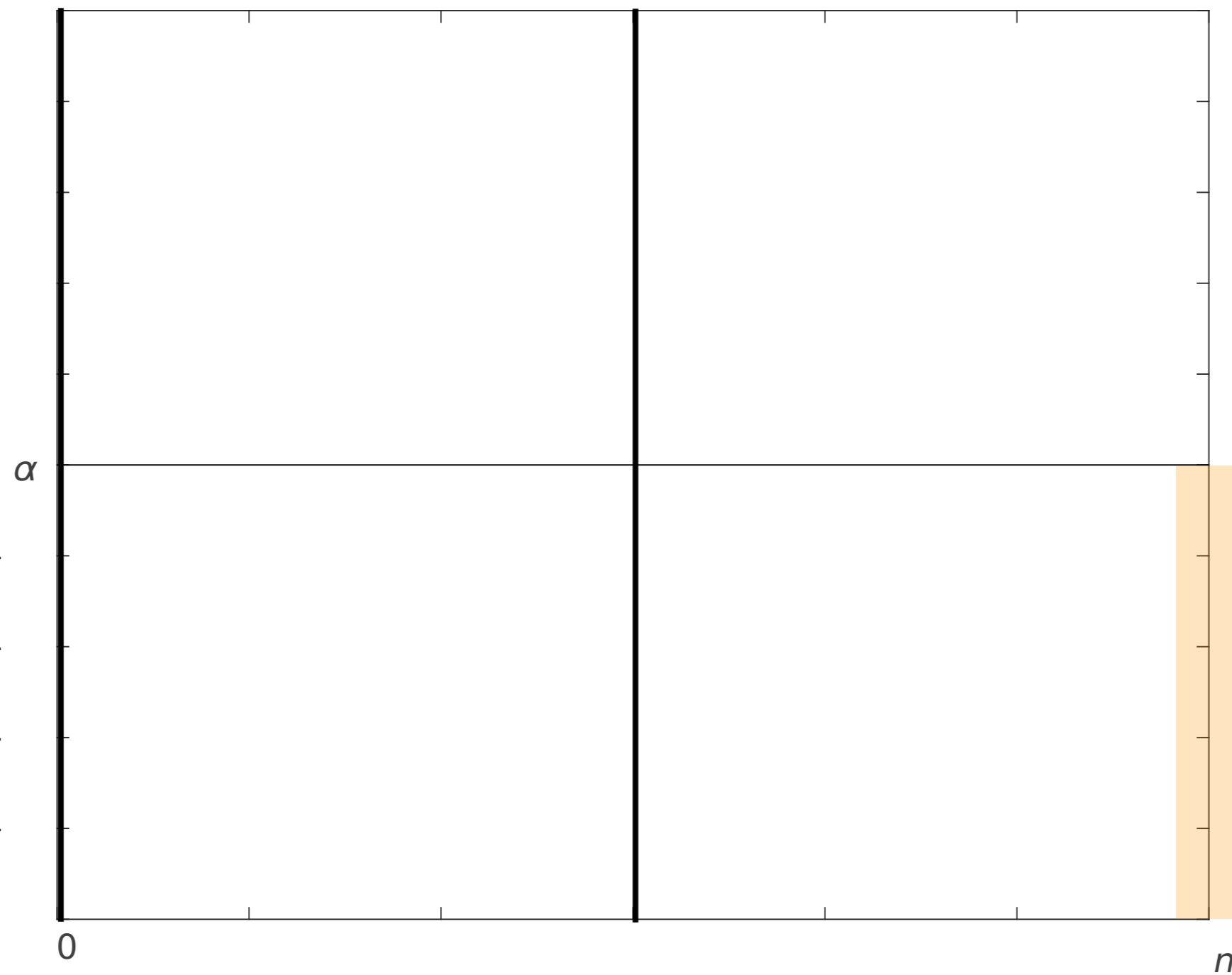
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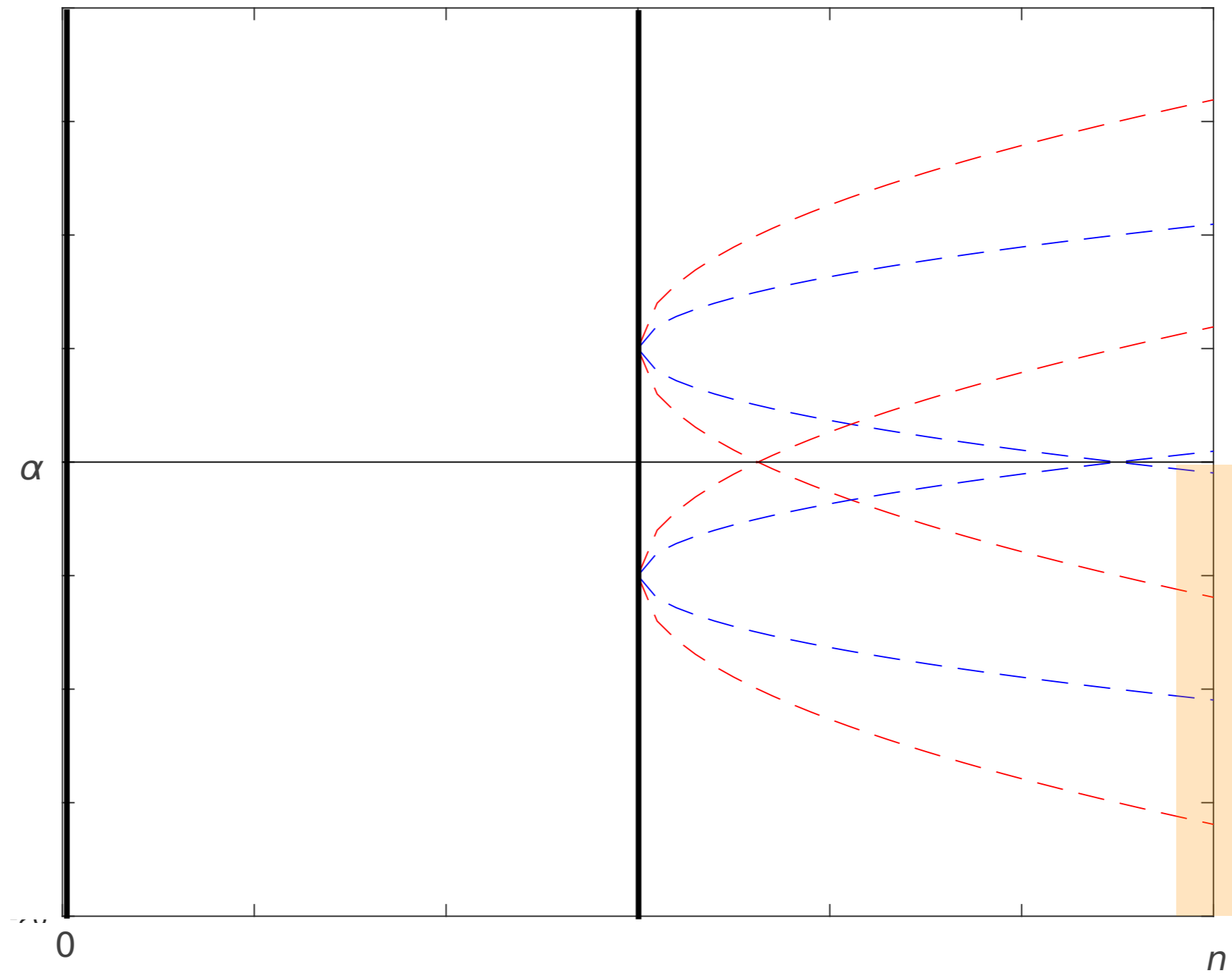
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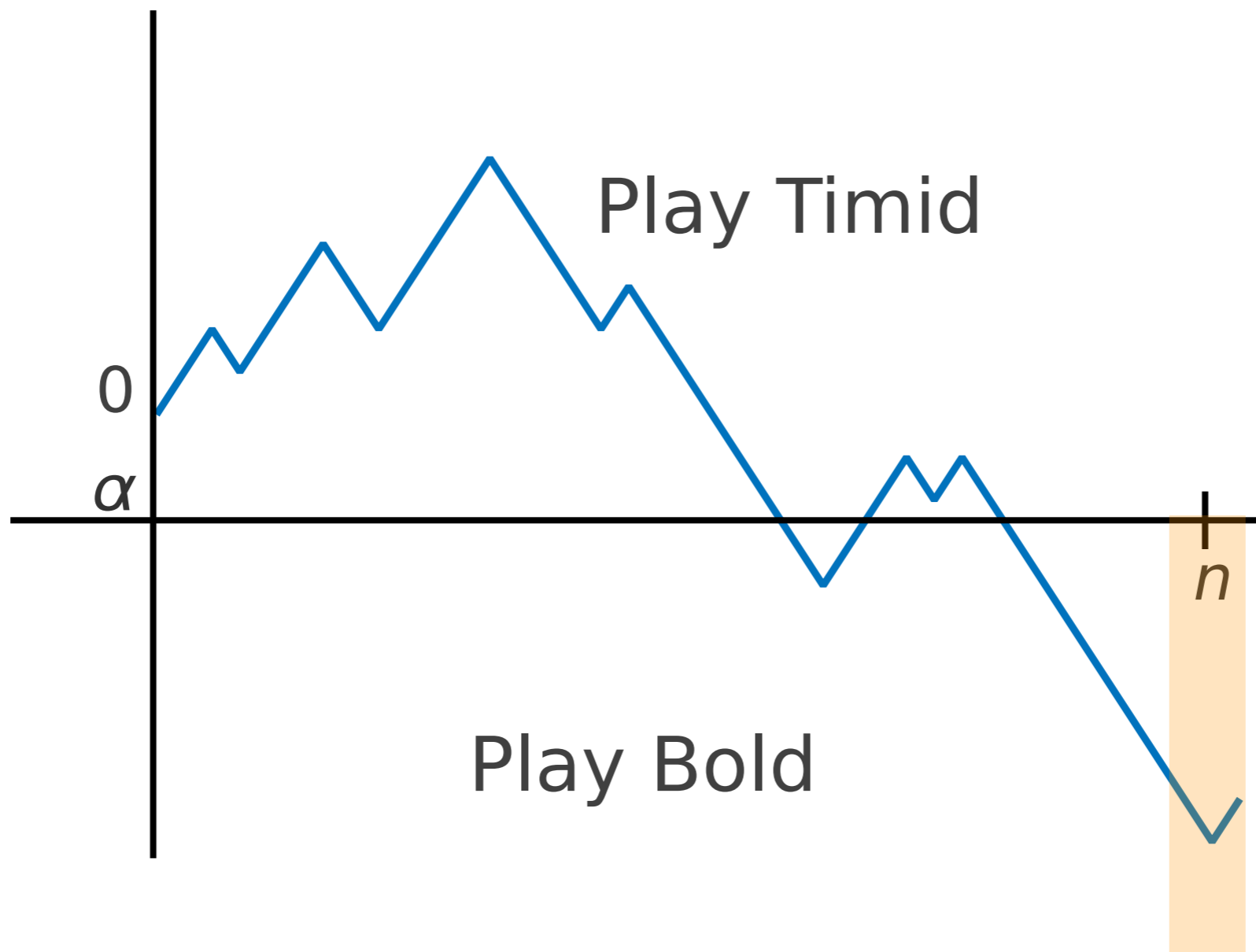
Strategies: Single Change-point



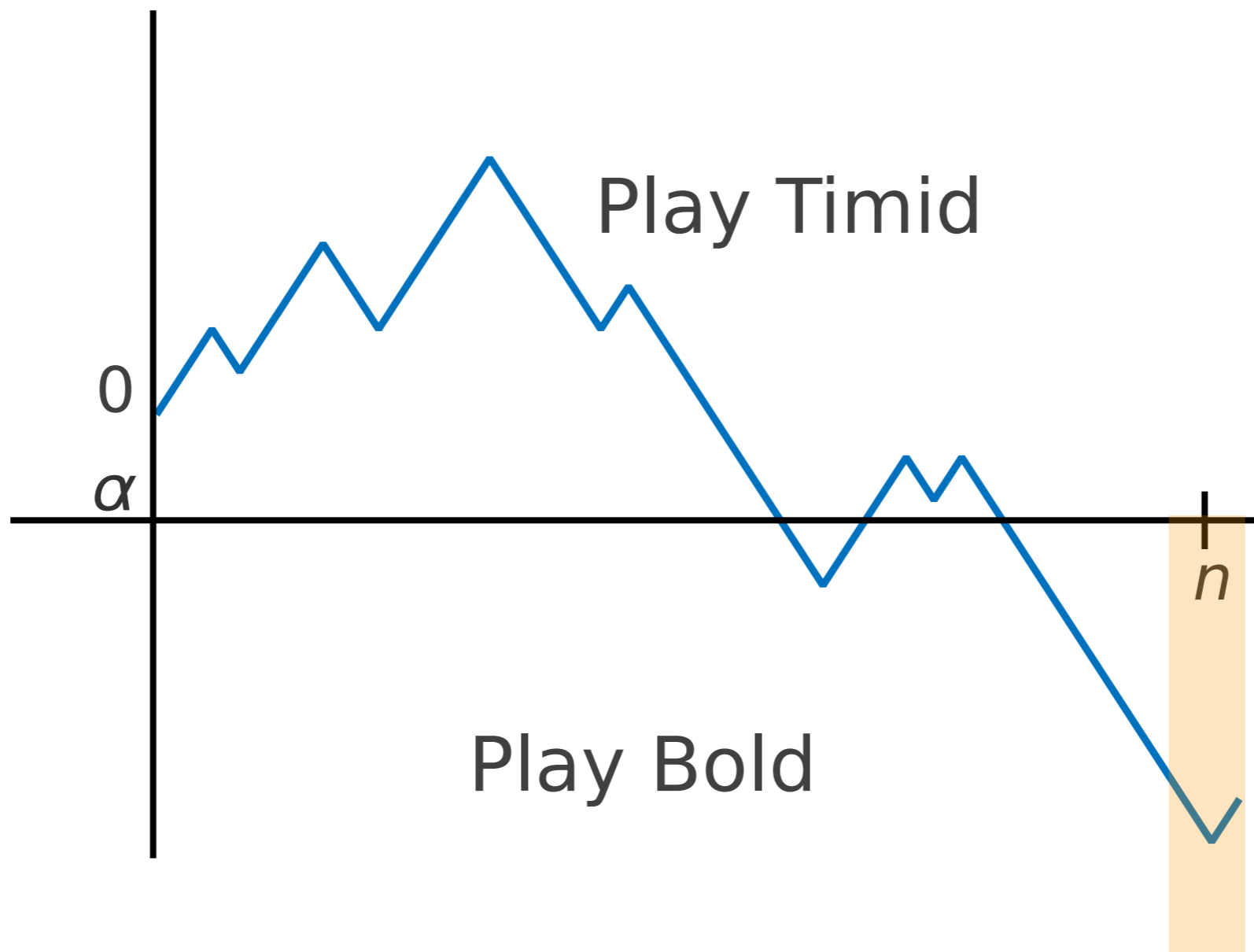
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More Generally



More Generally



With feedback, we can do better.

On the Web

FiveThirtyEight



Politics Sports Science & Health Economics **Culture**

FEB. 21, 2020, AT 8:00 AM

Can You Flip Your Way To Victory?

By [Zach Wissner-Gross](#)

Filed under [The Riddler](#)



Riddler Classic

From Abijith Krishnan comes a game of coin flipping madness:

You have two fair coins, labeled A and B. When you flip coin A, you get 1 point if it comes up heads, but you lose 1 point if it comes up tails. Coin B is worth twice as much — when you flip coin B, you get 2 points if it comes up heads, but you lose 2 points if it comes up tails.

To play the game, you make a total of 100 flips. For each flip, you can choose either coin, and you know the outcomes of all the previous flips. In order to win, you must finish with a positive total score. In your eyes, finishing with 2 points is just as good as finishing with 200 points — any positive score is a win. (By the same token, finishing with 0 or -2 points is just as bad as finishing with -200 points.)

If you optimize your strategy, what percentage of games will you win?
(Remember, one game consists of 100 coin flips.)

Extra credit: What if coin A isn't fair (but coin B is still fair)? That is, if coin A comes up heads with probability p and you optimize your strategy, what percentage of games will you win?

Submit your answer

RECOMMENDED

**Why Younger Democrats
Are Overwhelmingly
Rejecting Biden**

Trump Approval Ratings

UPDATED 2 HOURS AGO

Strategies: Continuous-Time

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▶ How to select $\sigma(\cdot, \cdot)$ to minimize $P(X(1) < \alpha)$?

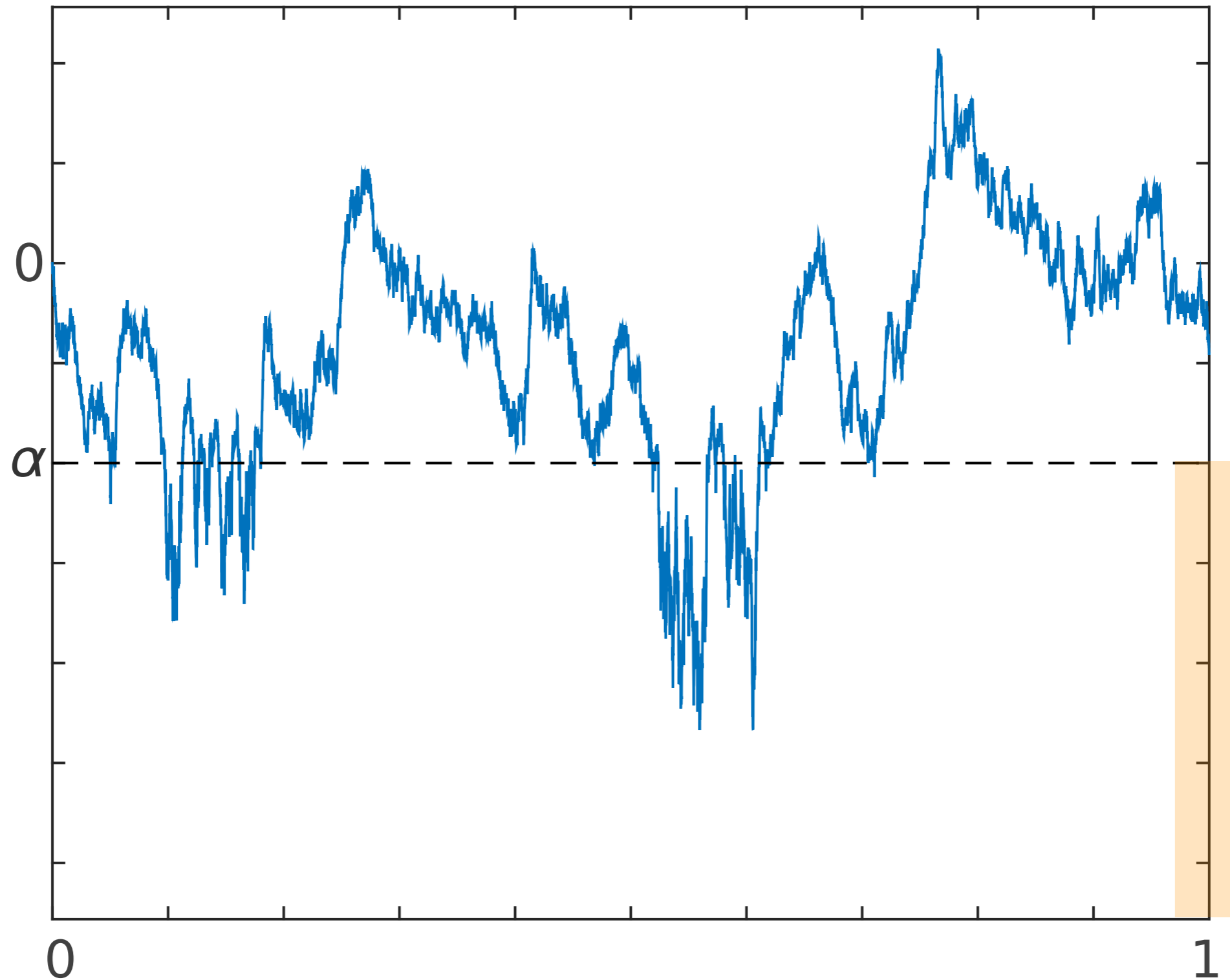
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where $\sigma(\cdot, \cdot) \in [\sigma_1, \sigma_2]$; $\sigma_1 > 0$
- ▶ How to select $\sigma(\cdot, \cdot)$ to minimize $P(X(1) < \alpha)$?
- ▶ **Theorem** (McNamara '83): The bang-bang controller

$$\sigma(x, s) = \begin{cases} \sigma_1 & \text{if } x \geq \alpha \\ \sigma_2 & \text{if } x < \alpha \end{cases}$$

is optimal.

In Simulation



In the Real World



In the Real World

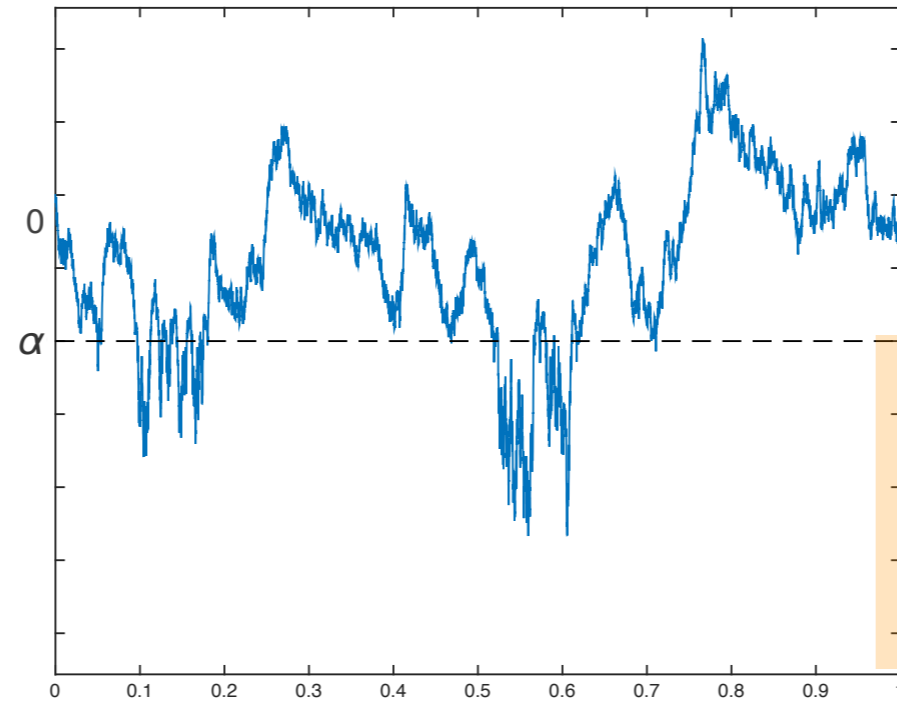


In the Real World

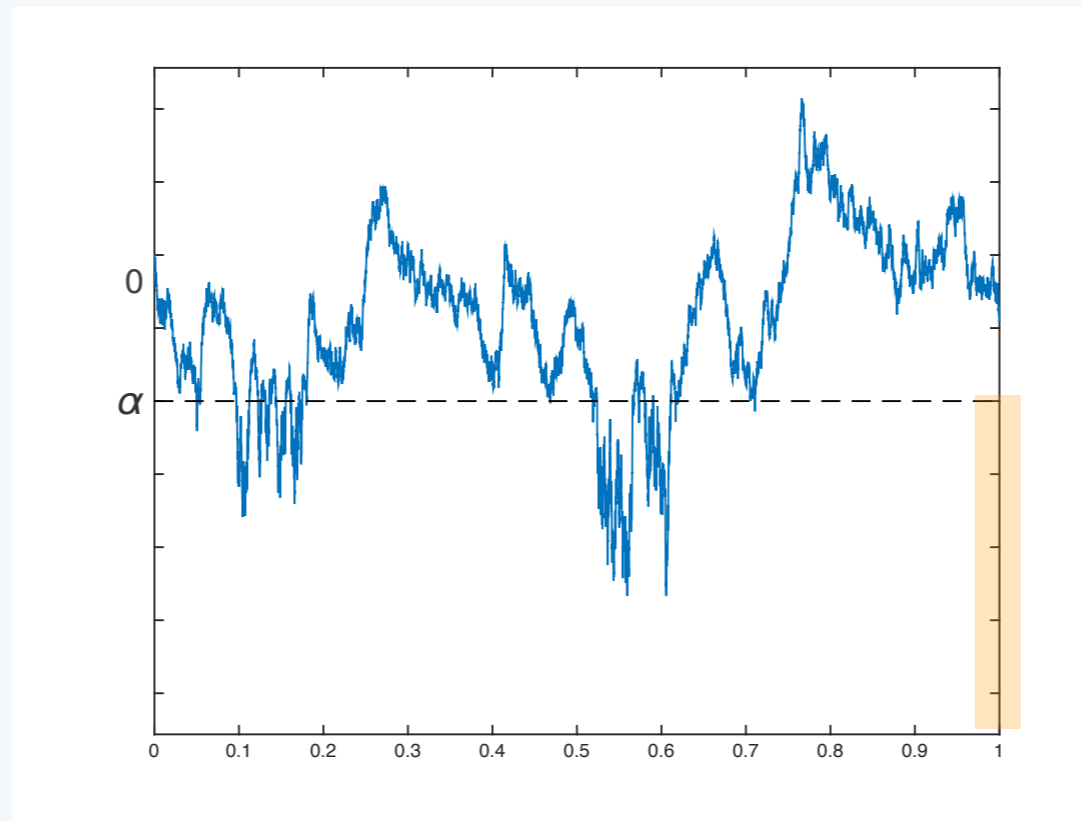


- ▶ McNamara '83: foraging animals

The McNamara Threshold

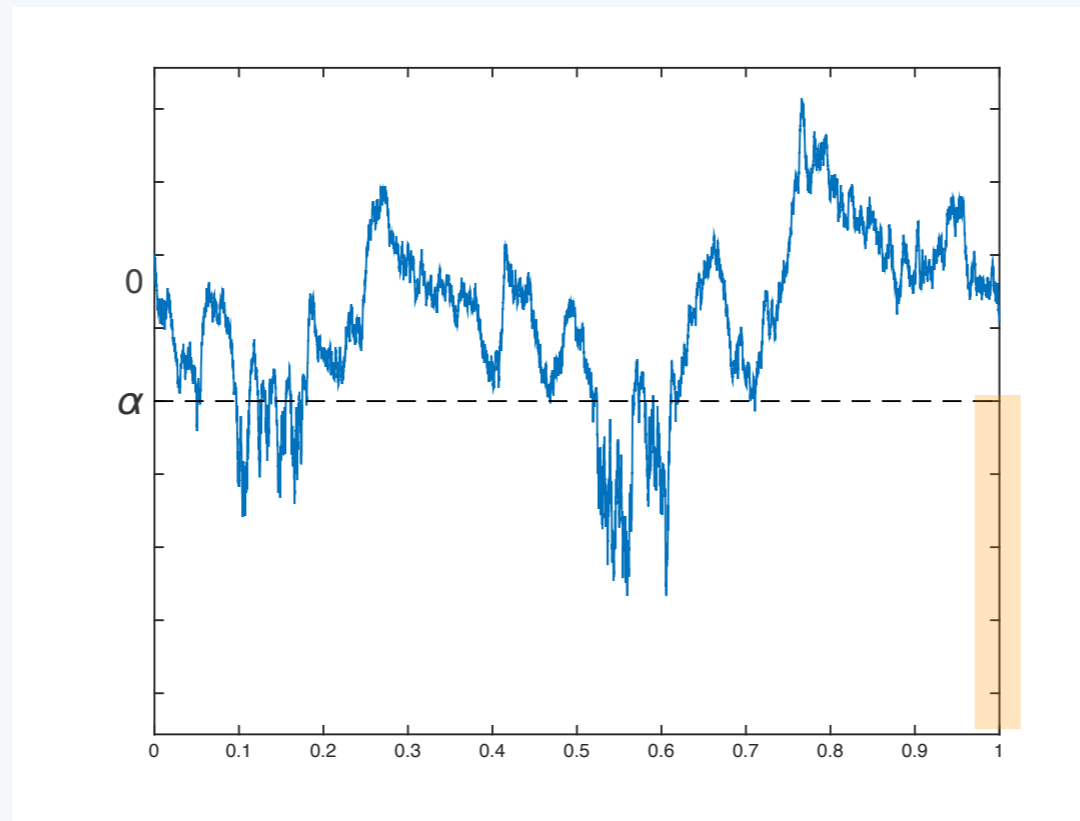


The McNamara Threshold



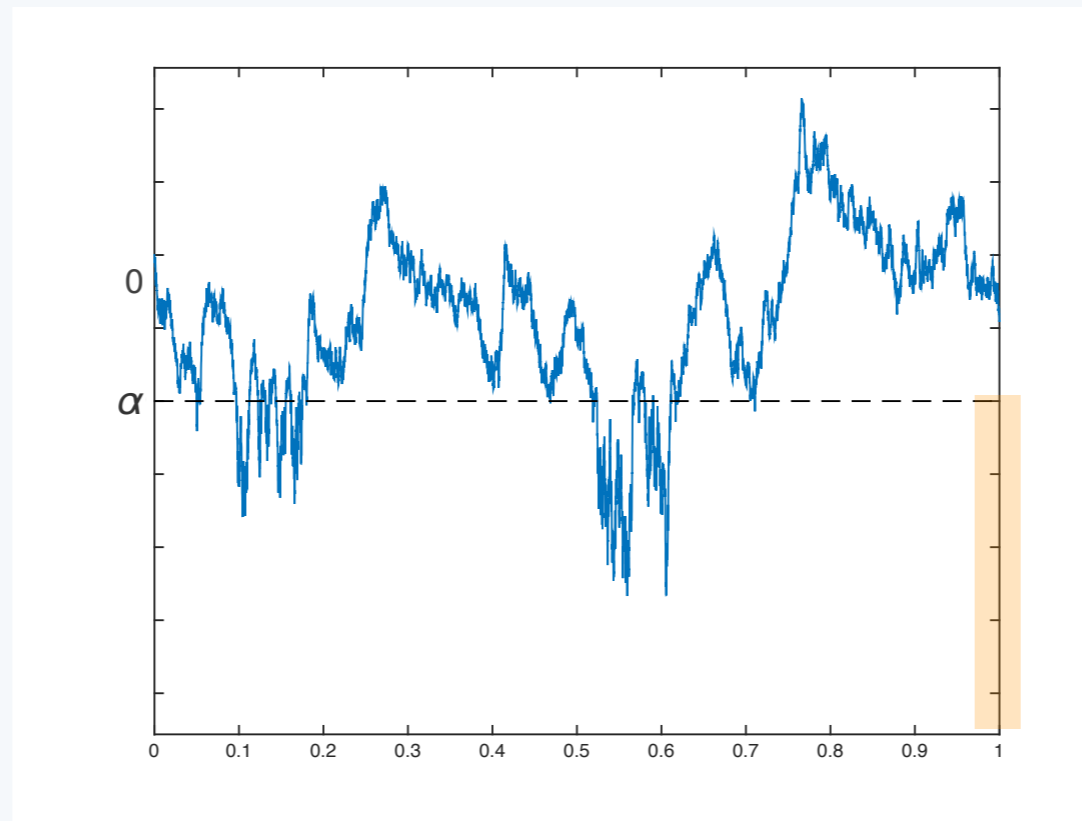
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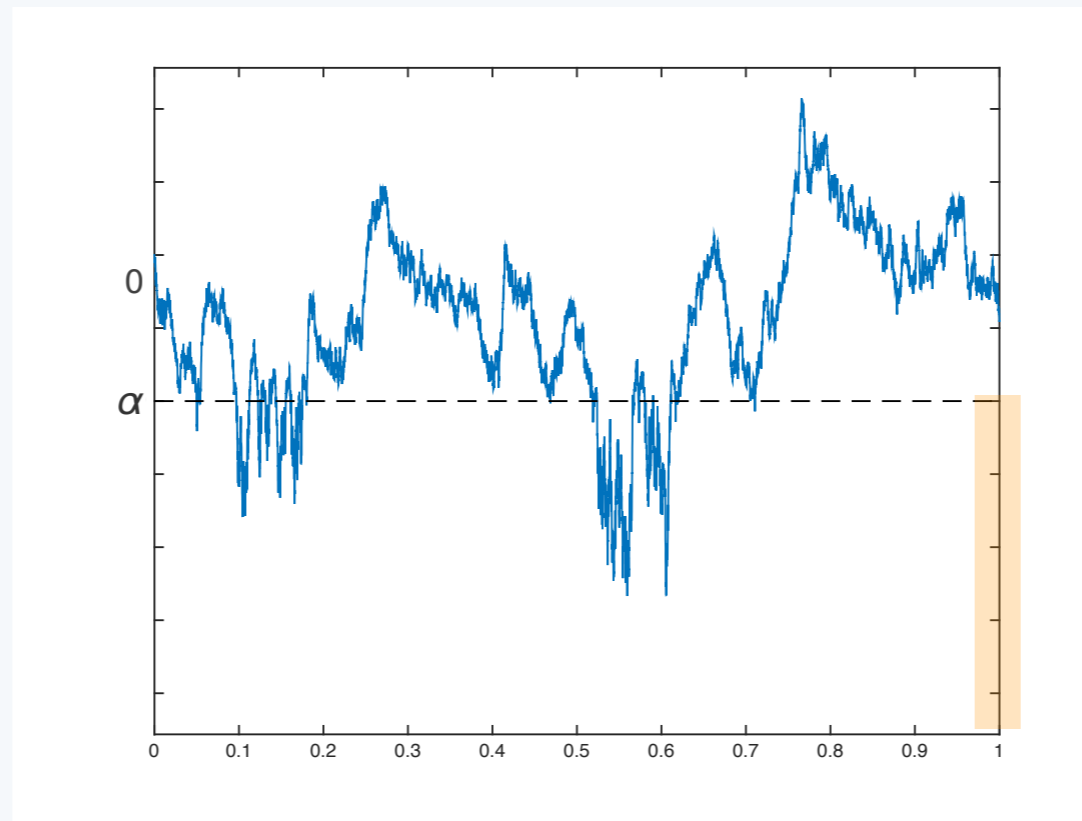
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- ▶ Let $\Gamma(\epsilon, \sigma_1, \sigma_2) = \max\{\alpha : \text{without feedback, } \Pr(\text{failure}) \leq \epsilon\}$.
- ▶ Both expressible in terms of inv. Gaussian CDF
- ▶ **Lemma:** $\Gamma(\epsilon, \sigma_1, \sigma_2) < \Gamma^{(fb)}(\epsilon, \sigma_1, \sigma_2)$ iff $\sigma_1 < \sigma_2$

A Key Lemma

- ▶ **Def:** a *controller* is a function

$$f : (\mathcal{X} \times \mathcal{Y})^* \rightarrow \mathcal{P}(\mathcal{X})$$

which along with the channel W defines a joint distribution

$$(f \circ W)(x^n, y^n) = \prod_{i=1}^n (f(x^{i-1}, y^{i-1}))(x_i) W(y_i | x_i)$$

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$$(f \circ W)(x^n, y^n) = \prod_{i=1}^n (f(x^{i-1}, y^{i-1}))$$

number of bits we commit to send (k)

- ▶ **Lemma** (cf. Shannon '57, Fong-Tan '17; Wang *et al.* '09; Blahut '86) with feedback, $\beta^{(fb)}(\epsilon)$, is the largest α such that

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with

A Key Lemma

- ▶ **Def:** a *controller* is a function

$f : (x^n, y^n) \rightarrow (x^n, y^n)$
 which along with the channel W defines a transmission function $(f \circ W)(x^n, y^n)$

actual
(realized)
amount of
information
that gets
through

number of
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send (k)

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- ▶ Non-feedback version as well.

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- ▶ Non-feedback version as well.
- ▶ \$64K question: can we control the variance of the increments?

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Fact:

$$PW = Q^* \text{ for all } P : I(P; W) = C$$

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$PW = Q^*$ for all

Let P_{\min} be a minimizer

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Compound dispersion if $V_{\min} < V_{\max}$. Otherwise simple dispersion.

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A channel with a unique capacity-achieving input distribution is necessarily simple dispersion.

A Compound Dispersion Example

$$W(y|x) = \begin{bmatrix} p & 0.5(1-p) & 0.5(1-p) \\ 0.5(1-p) & p & 0.5(1-p) \\ 0.5(1-p) & 0.5(1-p) & p \\ \hline q & 1-q & 0 \\ 0 & q & 1-q \\ 1-q & 0 & q \end{bmatrix}$$

if $p = 0.8$
and $q \approx 0.337$
then $V_{\min} = .102$
 $V_{\max} = .692$

A Compound Dispersion Example

$$W(y|x) = \left[\begin{array}{ccc|c} p & 0.5(1-p) & 0.5(1-p) & 1/3 \\ 0.5(1-p) & p & 0.5(1-p) & 1/3 \\ 0.5(1-p) & 0.5(1-p) & p & 1/3 \\ \hline q & 1-q & 0 & \\ 0 & q & 1-q & \\ 1-q & 0 & q & \end{array} \right] P_{\max}$$

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[Many more examples when we consider cost constraints ...]

SOCR without Feedback

- ▶ **Theorem 0:** (Strassen '62) For any DMC, the SOCR satisfies:

$$\beta(\epsilon) = \Gamma(\epsilon, \sqrt{V_{\min}}, \sqrt{V_{\max}})$$

SOCR without Feedback

- ▶ **Theorem 0:** (Strassen '62) For any DMC, the SOCR satisfies:

$$\beta(\epsilon) = \Gamma(\epsilon, \sqrt{V_{\min}}, \sqrt{V_{\max}})$$

- ▶ **Intuition:** By the key lemma, SOCR is the max α such that

$$\lim_{n \rightarrow \infty} \inf_f (f \circ W) \left(\sum_{i=1}^n \left(\log \frac{W(Y_i|X_i)}{(fW)(Y_i|Y^{i-1})} - C \right) \leq \alpha \sqrt{n} \right) < \epsilon$$

where f is “open-loop.” Intuitively, optimal choice *should* be:

$$\begin{cases} P_{\min} & \text{if } \Gamma(\epsilon, \sqrt{V_{\min}}, \sqrt{V_{\max}}) < 0 \\ P_{\max} & \text{if } \Gamma(\epsilon, \sqrt{V_{\min}}, \sqrt{V_{\max}}) > 0 \end{cases}$$

Second-Order Coding Rate w/ Feedback

- **Theorem 1** (Wagner-Shende-Altuğ '20): For any DMC with feedback,

$$\begin{aligned}\beta^{(fb)}(\epsilon) &\geq \Gamma^{(fb)}\left(\epsilon, \sqrt{V_{\min}}, \sqrt{V_{\max}}\right) \\ &> \Gamma\left(\epsilon, \sqrt{V_{\min}}, \sqrt{V_{\max}}\right) \text{ if } V_{\max} > V_{\min} \\ &= \beta(\epsilon)\end{aligned}$$

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- ▶ **Corollary** (Wagner-Shende-Altuğ '20): Feedback improves the second-order coding rate for any compound-dispersion DMC.

Proof of Theorem 1

Proof of Theorem 1

► Key lemma:

$$\lim_{n \rightarrow \infty} \inf_f (f \circ W) \left(\sum_{i=1}^n \left(\log \frac{W(Y_i|X_i)}{(fW)(Y_i|Y^{i-1})} - C \right) \leq \alpha \sqrt{n} \right) < \epsilon$$

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- ▶ Choose $f(x^k, y^k)$ to be capacity-achieving for each (x^k, y^k) :
 - Increment is zero mean

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- ▶ Show convergence to cont.-time controlled diffusion

- Not Lipschitz ...

- ▶ Apply McNamara's characterization of bang-bang controller

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- ▶ Select bang-bang f :

$$f(x^k, y^k) = \begin{cases} \text{Timid/Bold Coding} & (m > \alpha \sqrt{n}) \\ \text{Timid/Bold Coding} & (m \leq \alpha \sqrt{n}) \end{cases}$$

- ▶ Show convergence to cont.-time controlled diffusion

- Not Lipschitz ...

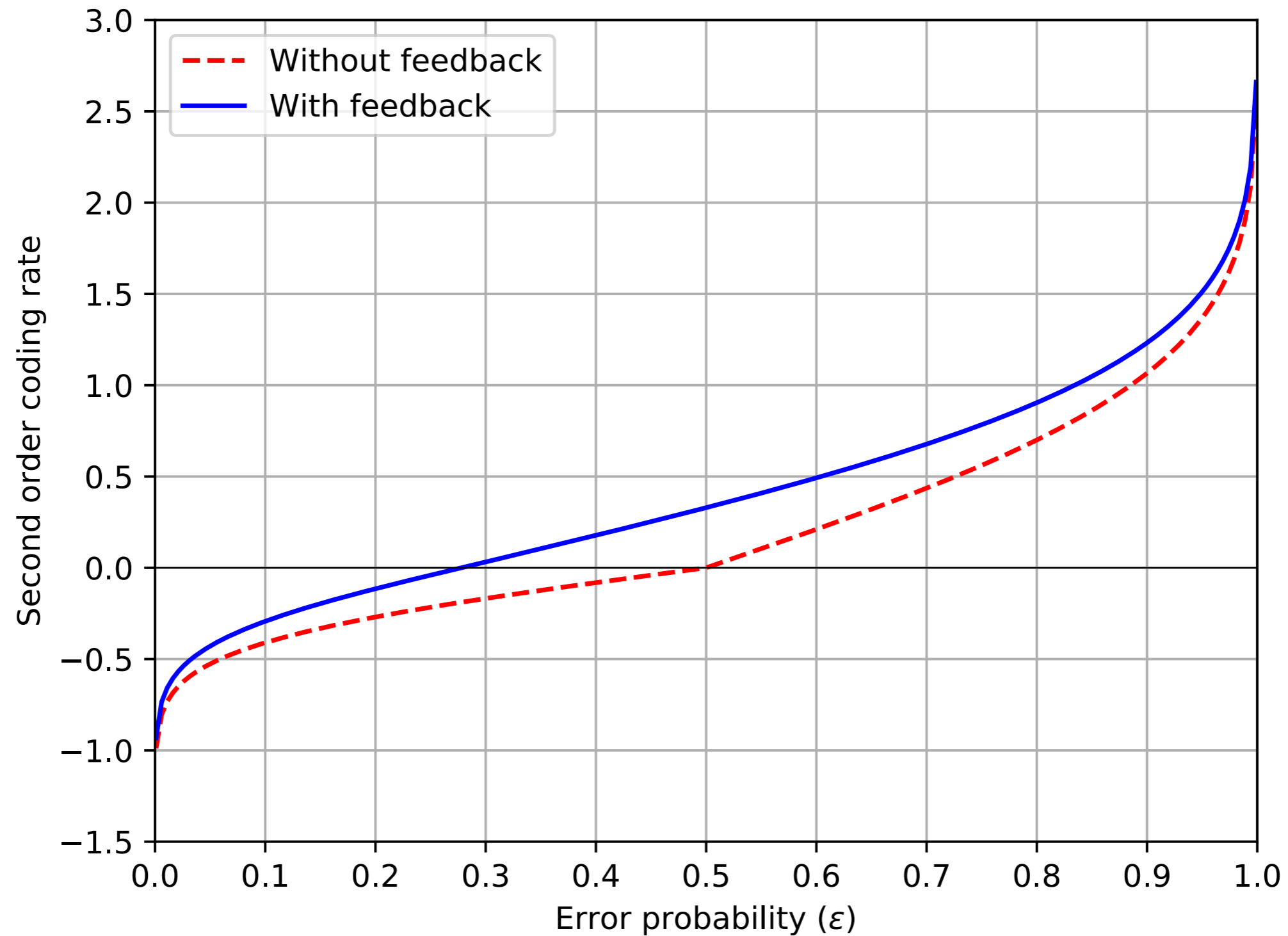
- ▶ Apply McNamara's characterization of bang-bang controller

A Compound Dispersion Example

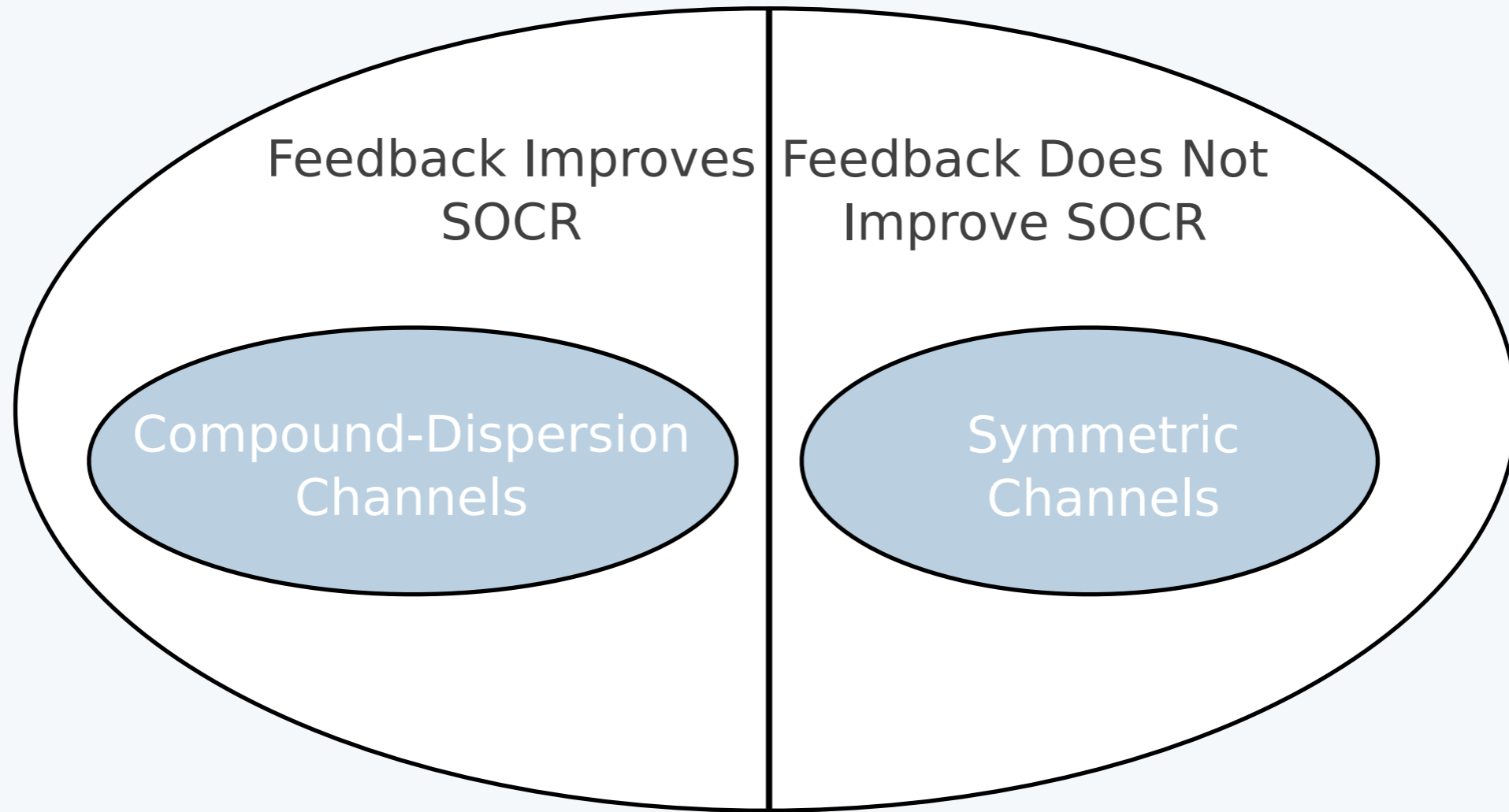
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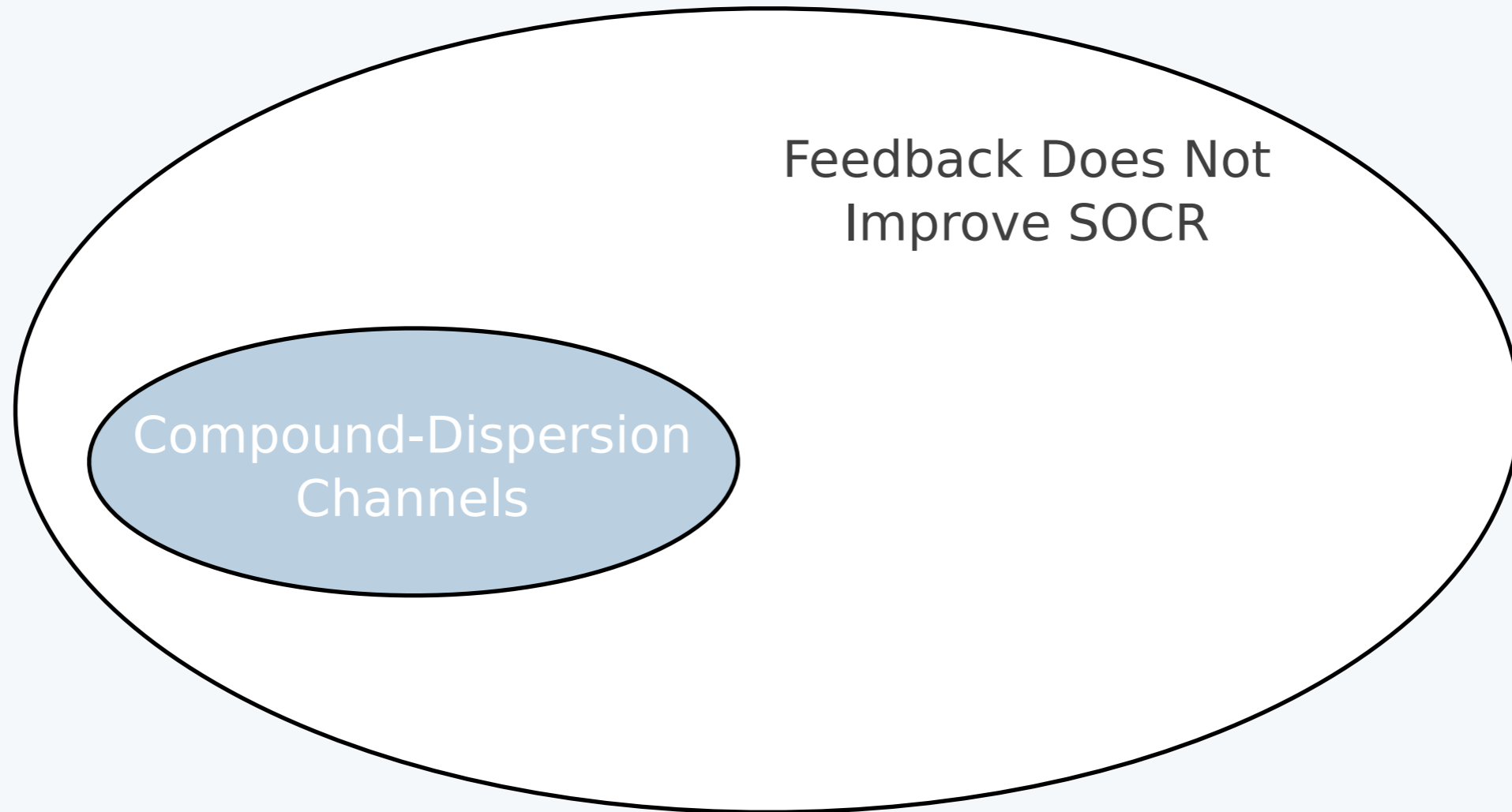
Numerical Example



When Does Feedback Help?



When Does Feedback Help?



- ▶ **Theorem 2** (Wagner-Shende-Altug): Feedback improves the second-order coding rate iff the channel is compound dispersion.

Proof of Theorem 2

Proof of Theorem 2

- By the key lemma, suffices to show that

$$\lim_{n \rightarrow \infty} \inf_f (f \circ W) \left(\sum_{i=1}^n \left(\log \frac{W(Y_i|X_i)}{(fW)(Y_i|Y^{i-1})} - C \right) \leq \Gamma(\epsilon, \sqrt{V_{\min}}, \sqrt{V_{\max}}) \cdot \sqrt{n} \right) > \epsilon$$

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- ▶ Can reduce to controller such that X^n is empirically capacity achieving w.h.p. [Fong-Tan '17]

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- ▶ Can reduce to controller such that X^n is empirically capacity achieving w.h.p. [Fong-Tan '17]
 - Simple dispersion \rightarrow sum of conditional variances of the terms in the sum given the past is fixed.

Proof of Theorem 2

- ▶ By the key lemma, suffices to show that

$$\lim_{n \rightarrow \infty} \inf_f (f \circ W) \left(\sum_{i=1}^n \left(\log \frac{W(Y_i|X_i)}{(fW)(Y_i|Y^{i-1})} - C \right) \leq \Gamma(\epsilon, \sqrt{V_{\min}}, \sqrt{V_{\max}}) \cdot \sqrt{n} \right) > \epsilon$$

- ▶ Can reduce to controller such that X^n is empirically capacity achieving w.h.p. [Fong-Tan '17]
 - Simple dispersion \rightarrow sum of conditional variances of the terms in the sum given the past is fixed.
- ▶ Apply martingale CLT [Bolthausen '82]

By How Much Does Feedback Help?

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[to apply McNamara,
need to switch to cont.-time]

DT martingale w.r.t.
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- ▶ **Theorem** (Strassen '67): If $\{S_n\}$ is a square-integrable martingale with $S_0 = 0$, then there exists a Brownian motion $B(\cdot)$ and a sequence of stopping times $0 = T_0 \leq T_1 \leq \dots \leq T_n$ such that

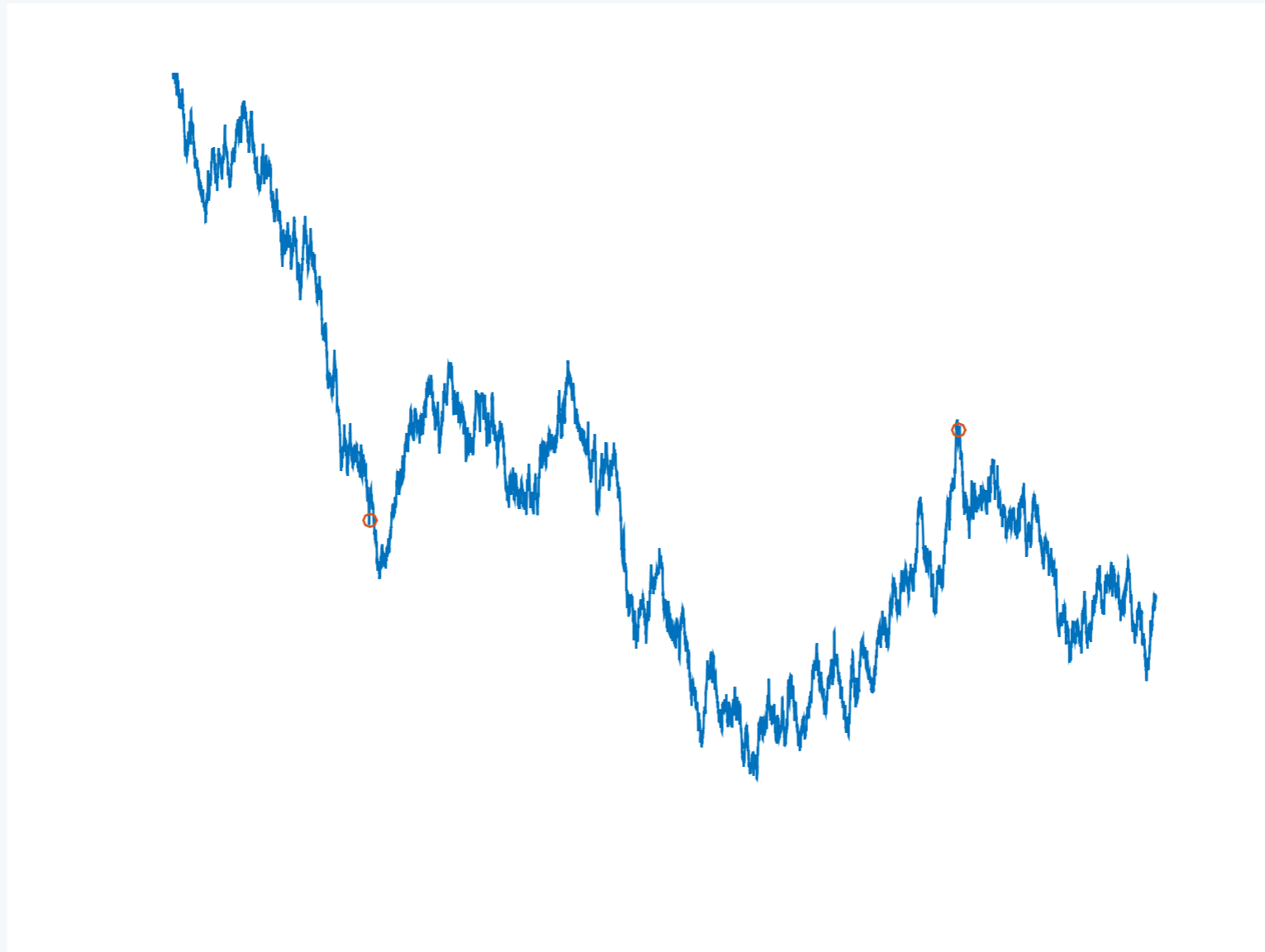
$$(S_0, S_1, \dots, S_n) \stackrel{d}{=} (B(T_0), B(T_1), \dots, B(T_n))$$

and

$$\begin{aligned} E[T_k - T_{k-1} | S_1, \dots, S_{k-1}, T_1, \dots, T_{k-1}] \\ = \text{Var}(S_k - S_{k-1} | S_1, \dots, S_{k-1}) \end{aligned}$$

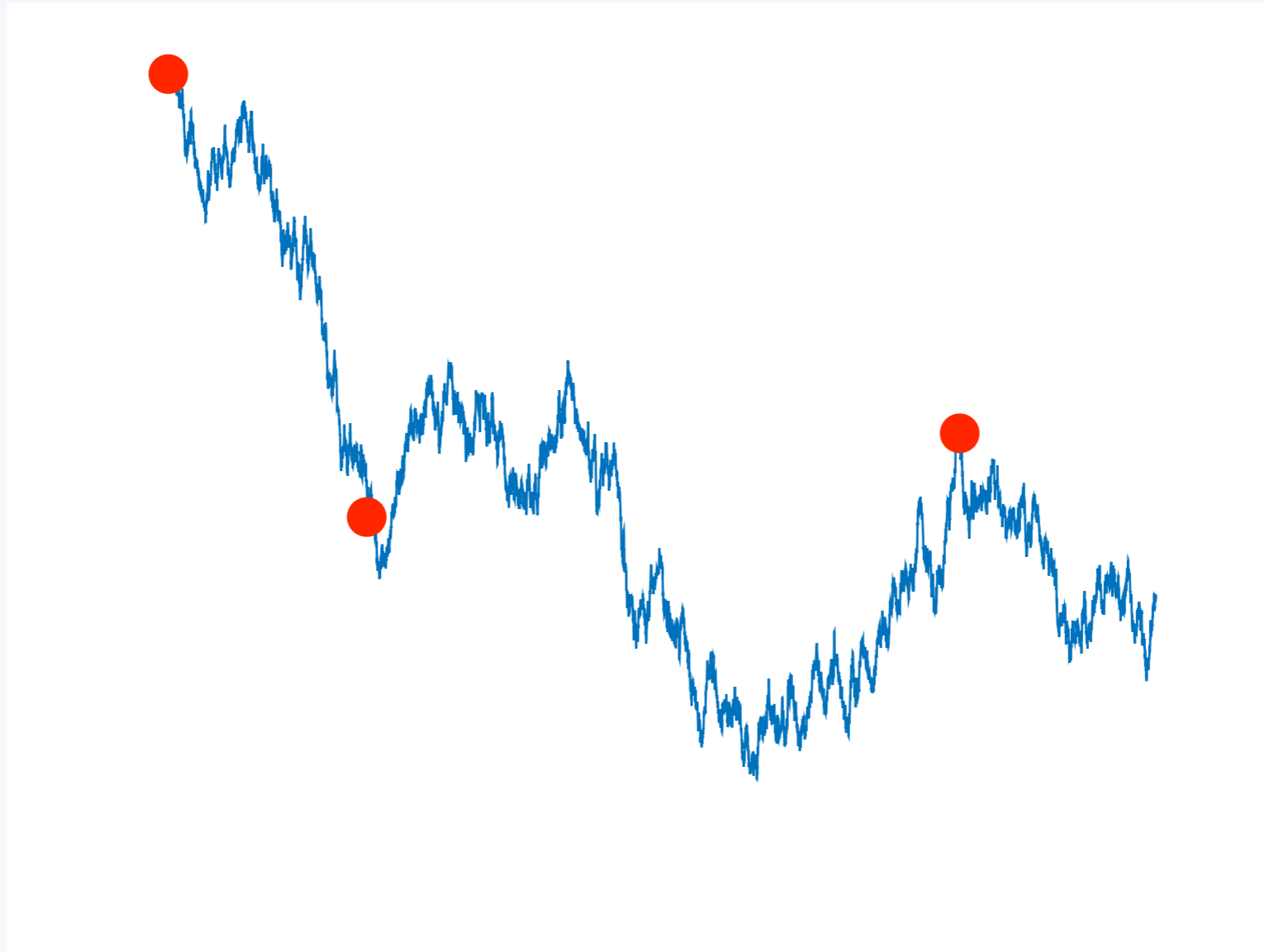
Proof of Theorem 3

- ▶ So view f as selecting stopping times:



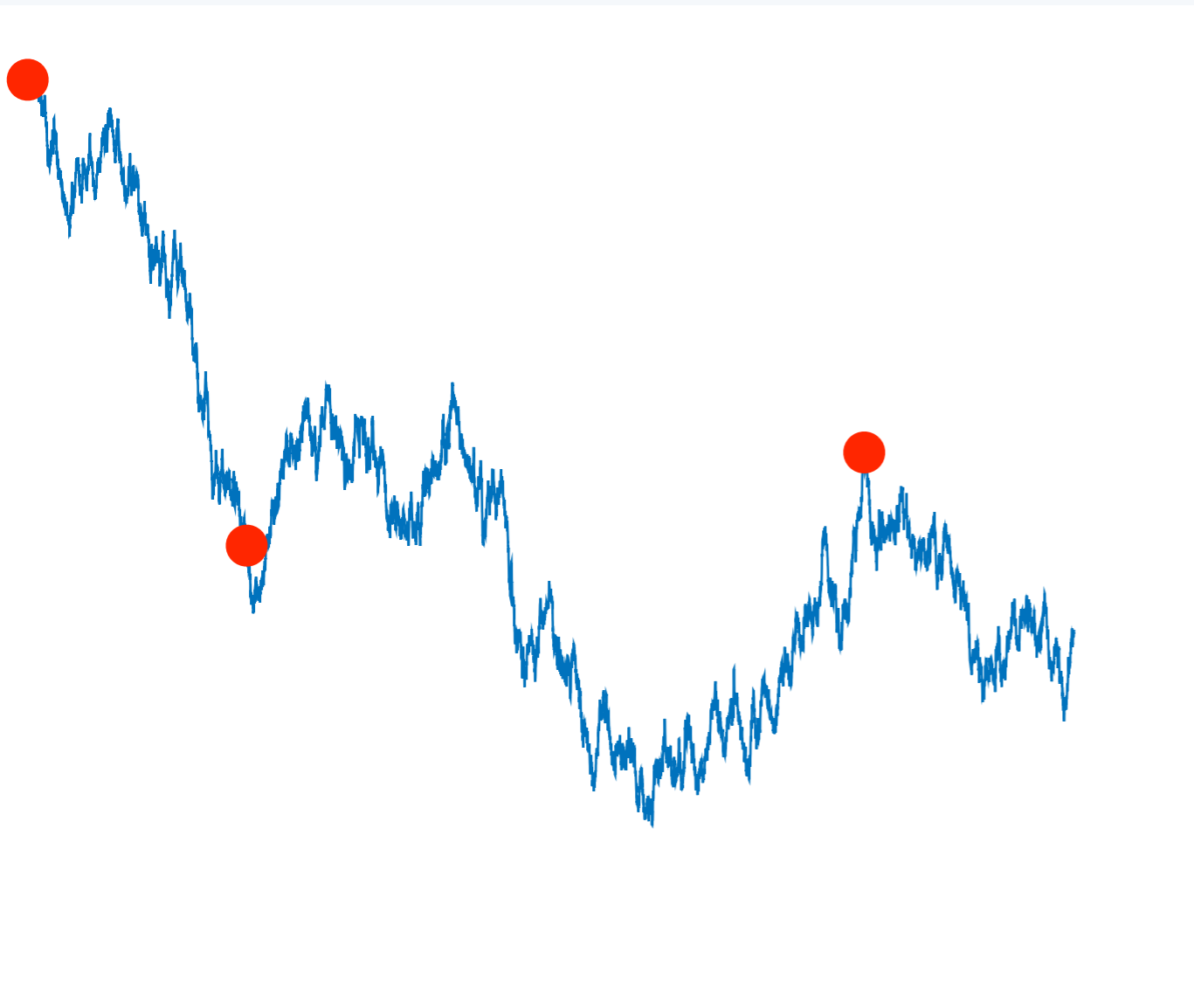
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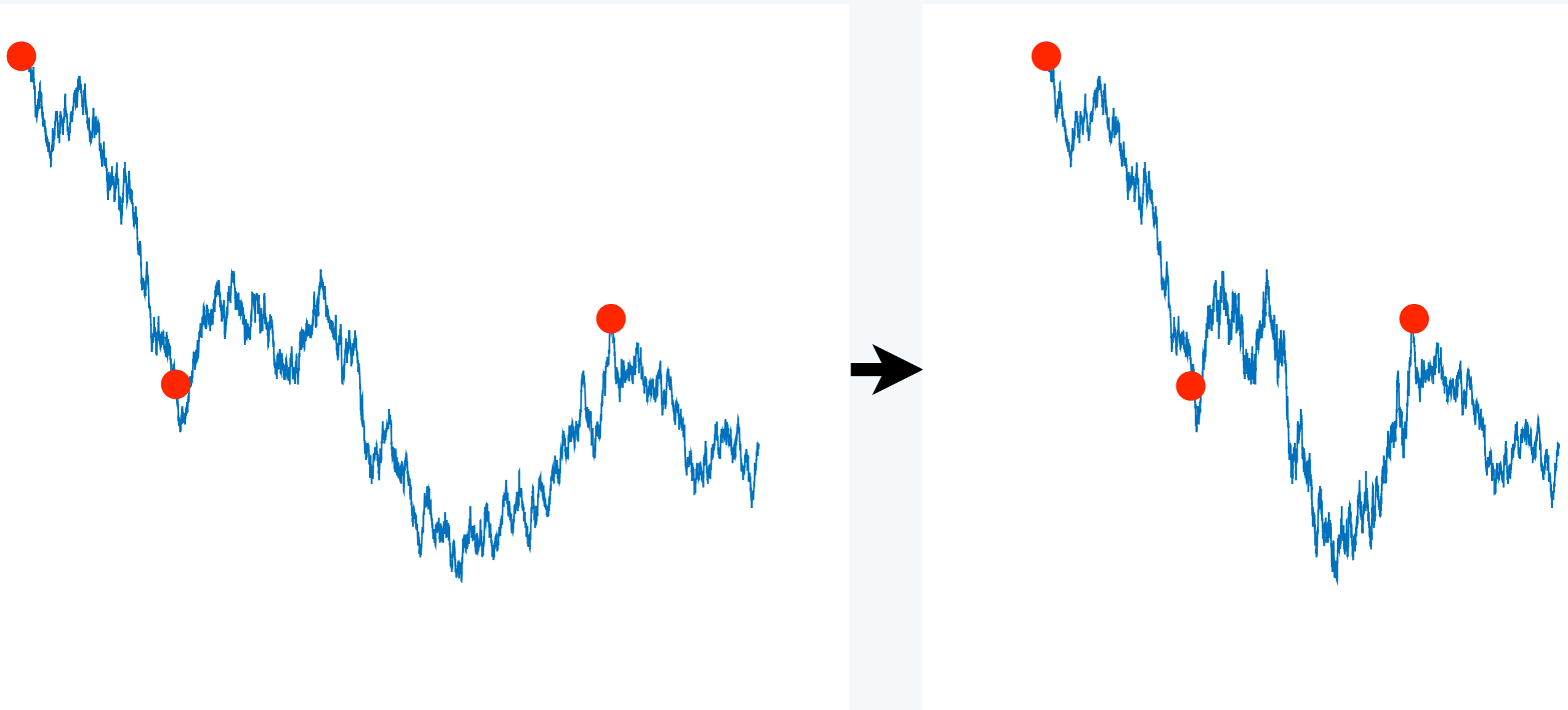
Proof of Theorem 3

- ▶ Then view f as speeding up the BM instead of waiting:



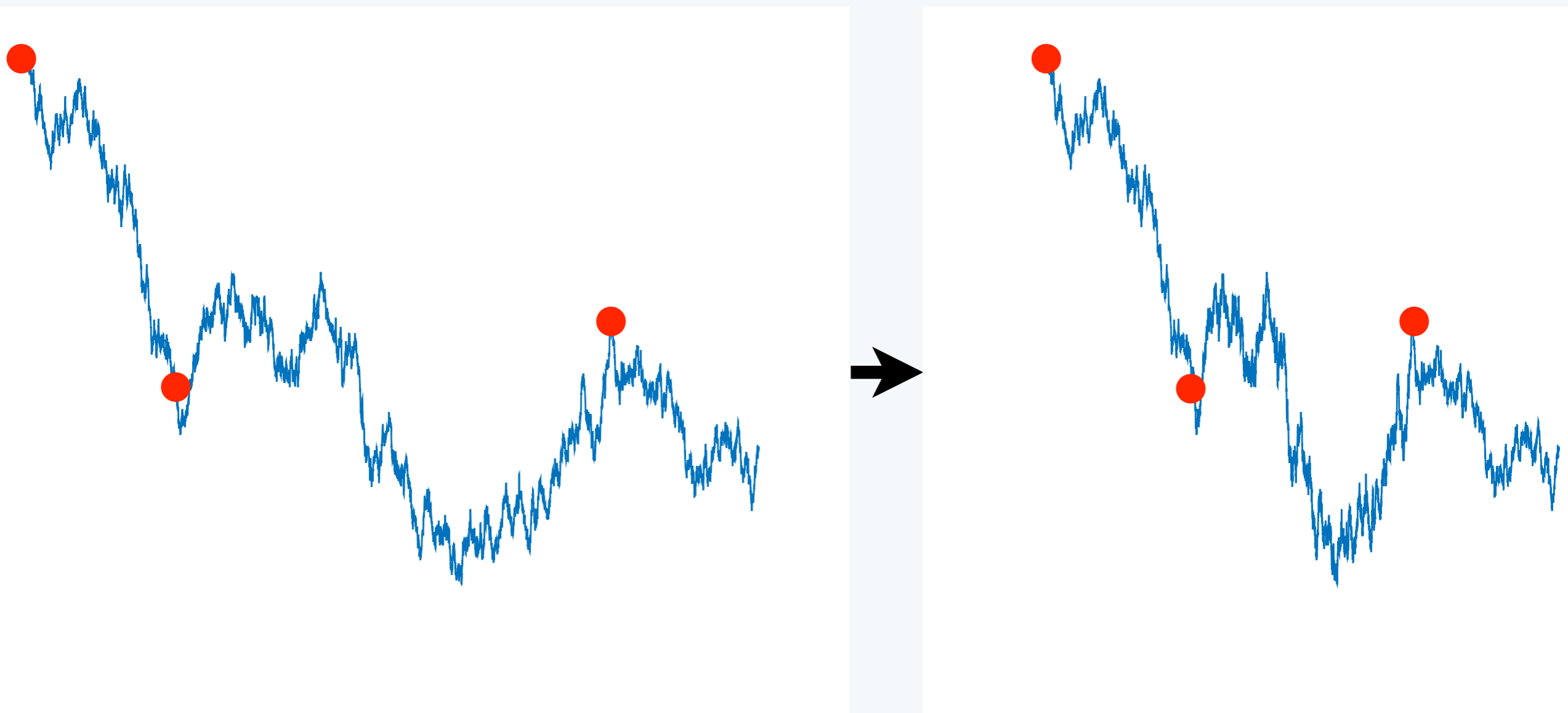
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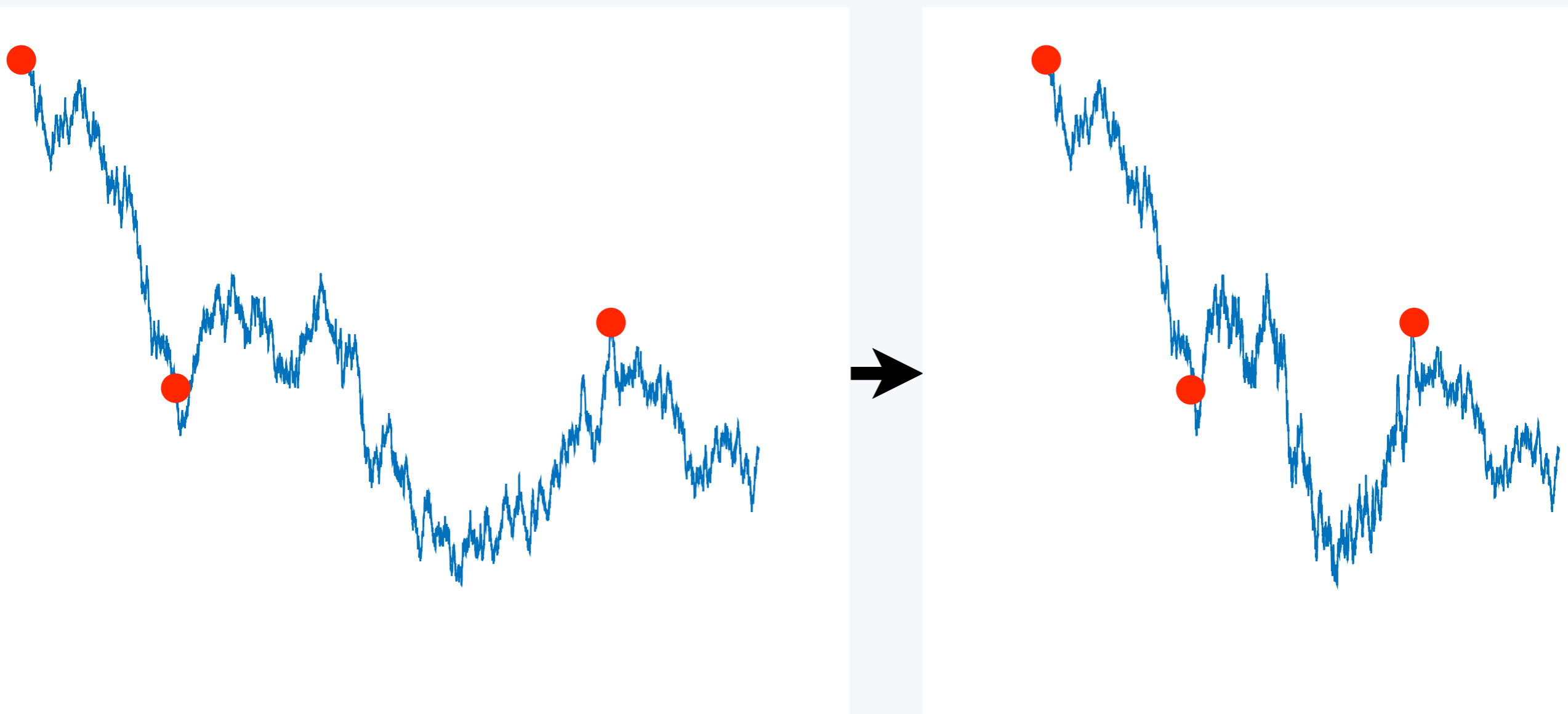
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- ▶ Such f is *nearly* a feasible scheme in McNamara's problem
- ▶ Make feasible and apply McNamara's optimality result

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A Compound Dispersion Example

$$W(y|x) = \left[\begin{array}{ccc} p & 0.5(1-p) & 0.5(1-p) \\ 0.5(1-p) & p & 0.5(1-p) \\ 0.5(1-p) & 0.5(1-p) & p \\ \hline q & 1-q & 0 \\ 0 & q & 1-q \\ 1-q & 0 & q \end{array} \right]$$

if $p = 0.8$
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then $V_{\min} = .102$
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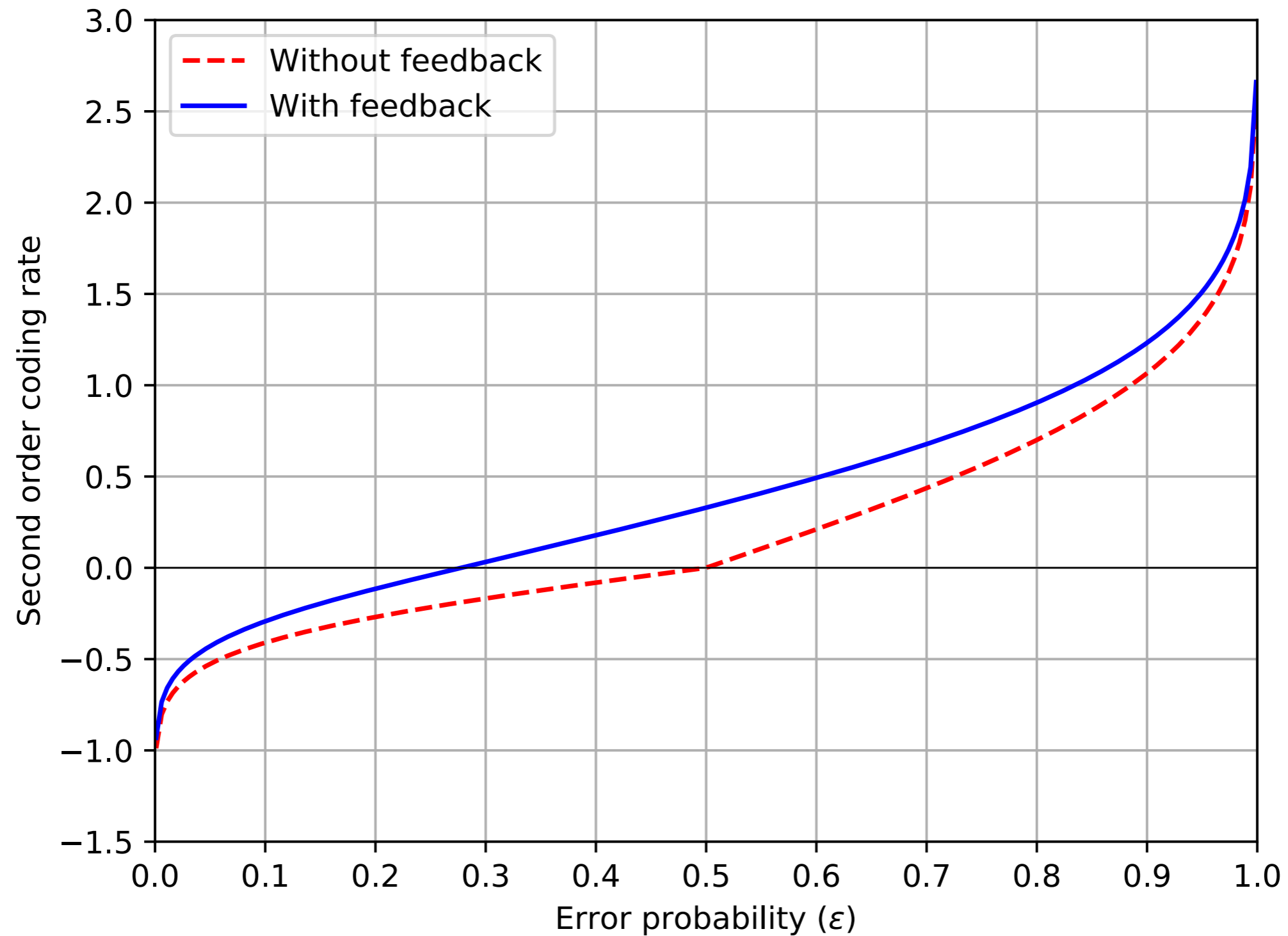
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... so the upper bound is tight in this case.

Numerical Example

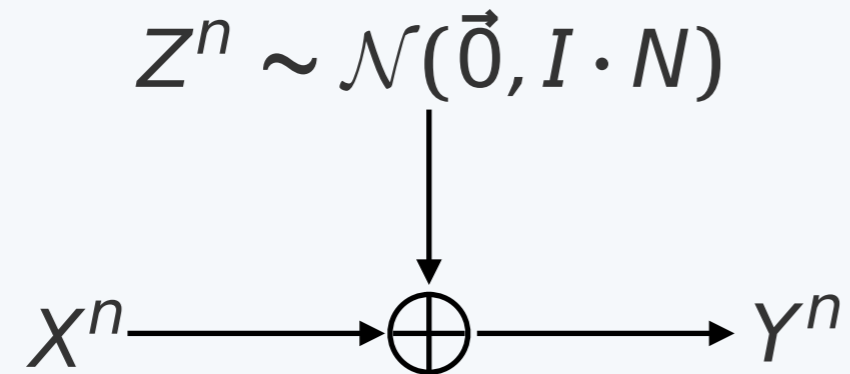


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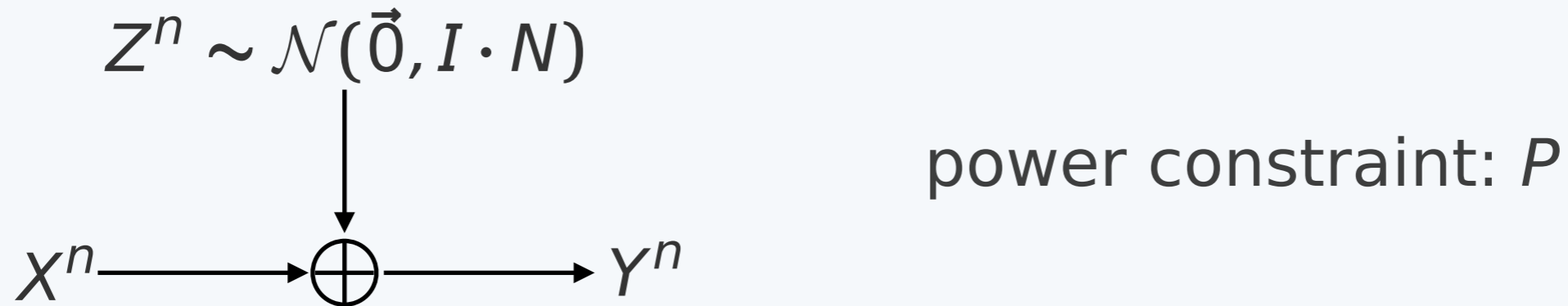
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The AWGN



power constraint: P

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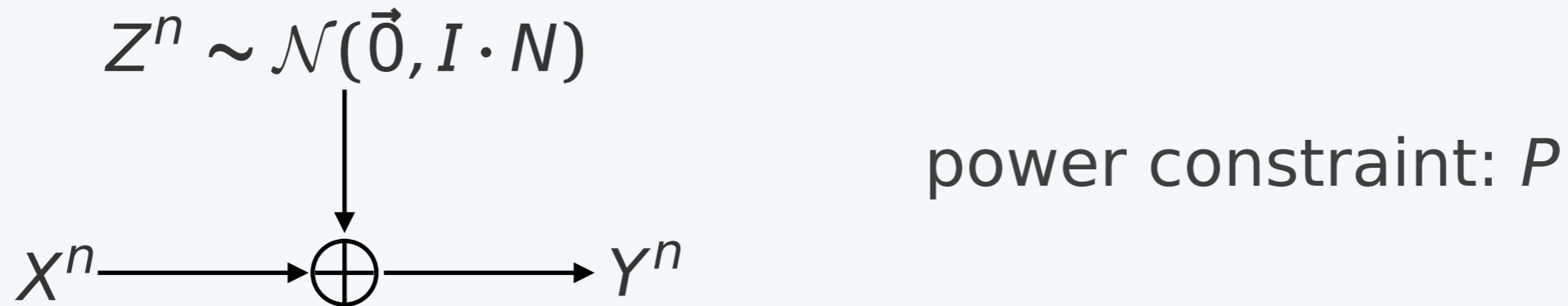
If X^n is drawn uniformly from the radius- \sqrt{nP} sphere:

$$\frac{1}{n} \text{Var} \left[\log \frac{W(Y^n | X^n)}{Q^*(Y^n)} \right] = \frac{P(P + 2N)}{2(P + N)^2}$$

If X^n is drawn i.i.d. $\mathcal{N}(0, P)$:

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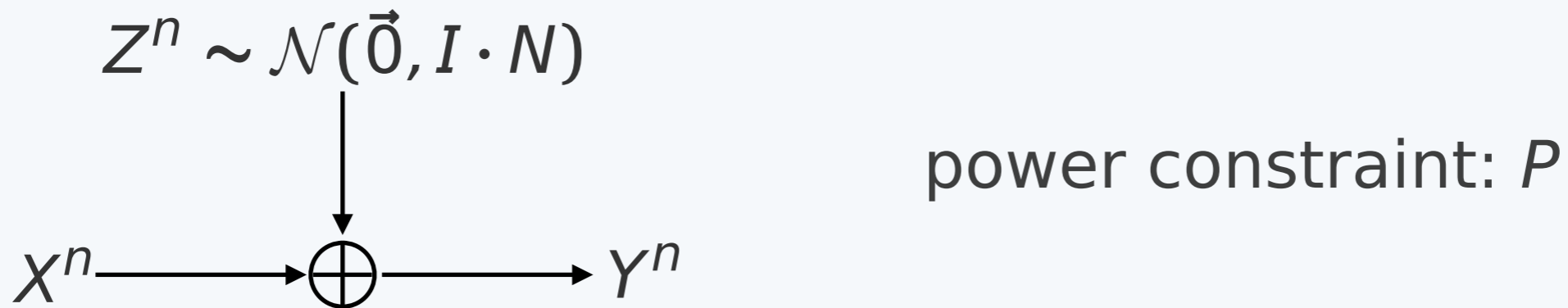
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[Similarly for any DMC with an active cost constraint]

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 - ▶ *Use timid/bold coding*